

# Ch: 1,2

## Passive elements

	R	L	C
Voltage (v)	$Ri$	$L \frac{di}{dt}$	$\frac{1}{C} \int_{t_0}^T i dt + v(t_0)$
Current (i)	$\frac{V}{R}$	$\frac{1}{L} \int_{t_0}^T v dt + i(t_0)$	$C \frac{dv}{dt}$
Power, $P=vi$	$i^2 R, \frac{V^2}{R}$	$Li \frac{di}{dt}$	$Cv \frac{dv}{dt}$
<p>"حب لا يسعد الناس يجعلك تبخ وتغفل ما لم تكن تتوقع فعله"</p> <p><del>*energy stored</del> (مخزنات)</p>			
energy stored	0	$\frac{1}{2} Li^2$	$\frac{1}{2} C v^2$
AC condition	$V=IR$	$V_L = I X_L = I \omega L$	$V_C = I X_C = \frac{I}{\omega C}$

## ملاحظات

\* تأثير C/L يظهر في الفترة الانتقالية سواء في DC أو AC أما هذا يظهر

في AC طبيعي.

\* المقاومة لا تخزن الطاقة وإنما تبددها.

\* الملف يخزن الطاقة في شكل مغناطيسي.

\* المكثف يخزن الطاقة في شكل كهربائي.

\* An Inductor doesnot permit as instantaneous change in its terminal current. التيار لا يسمح بتغير لحظي في التيار

\* An capacitor doesnot permit an instantaneous change in its terminal voltage.

\* An Resistance permit an instantaneous change in its terminal voltage and current.

### At steady state

\* Inductor appears as a short circuit in relation to constant terminal current.

\* Capacitor appears as open circuit in relation to constant terminal voltage.

### Active elements

- Independent current source. مصدر يعطي تيار مهما حدث

- Dependent current source. يعطي تيار قيمته تعتمد على تيار آخر في الدائرة.

### Types of circuits

#### (1) First order

\* RL - RC circuits [ (natural - step) response ] نوع دراستهم

#### (2) second order

RLC circuits



## Response

الإستجابة الناتجة عن تغير ما

① natural response.

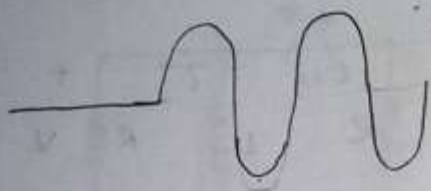
\* للدائرة الكهربائية بغير مصدر (active) وتعمل استجابة لتغير ما تحت تأثير الطاقة المخزنة.

② step response.

\* تعرفت الدائرة الكهربائية لتغير ما بعد أن كان ثابتاً.

③ Ac response.

\* لو المصدر كان (Ac) بعد أن كان المصدر = ديفر. ومفترض شرط أن الموجة تكون (sinwave) فقط



\* Any differential equation has four elements:-

① Independent variable.

متغير مستقل (الذي يتم عليه التفاضل)

$$(t) \leftarrow \frac{di}{dt}$$

② Dependent variable

③ Parameters or Coefficients. معلومات المتغير التابع، وثوابلاته

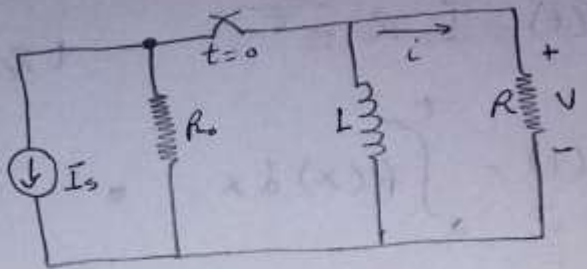
④ Forcing function or disturbance.

← اللحظة التي تسبق تغير حالة ال switch مباشرة.

← اللحظة التي تلي تغير حالة ال switch مباشرة.

# Natural Response of First Order RL circuit

\* قبل فتح المفتاح كانت الدائرة مستقرة  
فكان التيار  $I_0$  يمر بأكمله في الملف فتكون  
الطاقة المخزنة  $(\frac{1}{2}LI^2)$



at:  $t < 0$

$$I_0 = I_0$$

at:  $t \geq 0$

$$L \frac{di}{dt} + iR = 0$$

$$\frac{di}{dt} = \frac{-iR}{L}$$

$$\int_{I_0}^{i(t)} \frac{di}{i} = \int_0^t \frac{-R}{L} dt$$

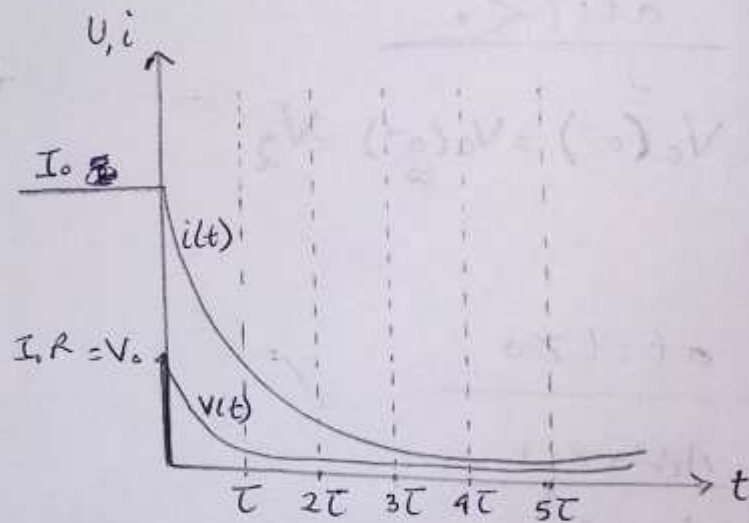
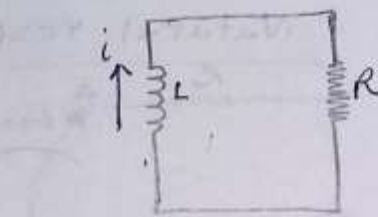
$$\ln i(t) - \ln I_0 = \frac{-R}{L} t$$

$$\frac{i(t)}{I_0} = e^{\frac{-R}{L} t}$$

$$i(t) = I_0 e^{\frac{-t}{\tau}} \quad t \geq 0$$

$$v(t) = I_0 R e^{\frac{-t}{\tau}} \quad t \geq 0^+$$

$$\tau = \frac{L}{R}$$



$$P = vi$$

$$P(t) = I_0^2 R e^{\frac{-2t}{\tau}}$$

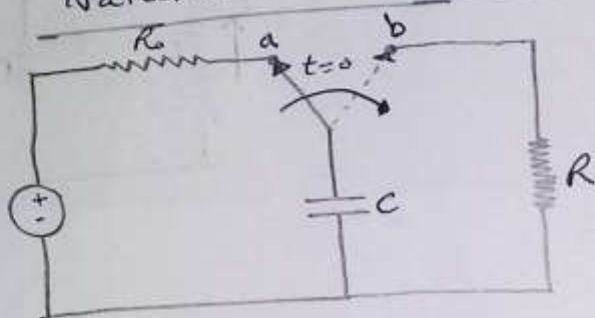
$$t \geq 0^+$$

$$W(t) = \int_0^t P(x) dx$$

$$W(t) = \frac{\tau}{2} I_0^2 R (1 - e^{-2t/\tau})$$

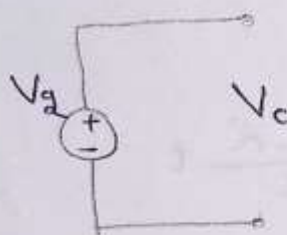
$$W(\infty) = \frac{\tau}{2} I_0^2 R = \frac{1}{2} L I_0^2$$

Natural response of RC circuit



at:  $t < 0$

$$V_C(0^-) = V_C(0^+) = V_g$$



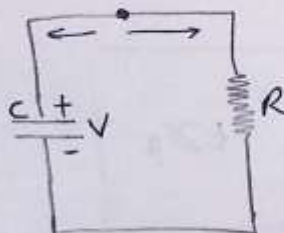
at:  $t \geq 0$

Apply Kcl

$$i_R + i_C = 0$$

$$C \frac{dv}{dt} + \frac{V}{R} = 0$$

$$\frac{dv}{dt} = \frac{-V}{RC}$$



5



$$\int_{V_c(0)}^{V(t)} \frac{dV}{V} = \int_0^t \frac{-1}{RC} dt$$

$$\ln V(t) - \ln V_c(0) = \frac{-t}{RC}$$

$$\frac{V(t)}{V_c(0)} = e^{-t/\tau}$$

$$\tau = RC$$

$$V(t) = V_c(0) e^{-t/\tau} \quad t \geq 0$$

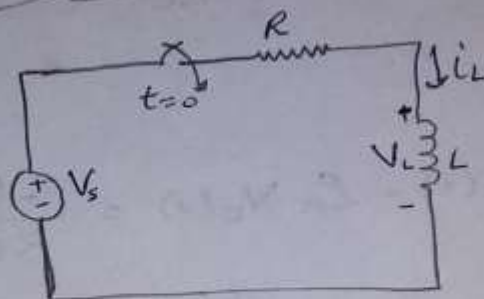
$$i(t) = \frac{V_c(t)}{R} = \frac{V_c(0)}{R} e^{-t/\tau}$$

$$P(t) = i^2(t) R = \frac{V_c(0)^2}{R} e^{-2t/\tau}$$

$$W(t) = \int_0^t P(t) dt$$

$$W(t) = \frac{1}{2} C V_0^2 (1 - e^{-2t/\tau})$$

# step response of an RL circuit



At  $t < 0$

$$i_L(0) = I_0$$

at  $t \geq 0$

Apply KVL

$$V_s = iR + L \frac{di}{dt}$$

$$\frac{di}{dt} = \frac{V_s - iR}{L} = \frac{-R}{L} \left( i - \frac{V_s}{R} \right)$$

$$I_0 \int_{I_0}^{i(t)} \frac{di}{i - \frac{V_s}{R}} = \int_0^t \frac{-R}{L} dt$$

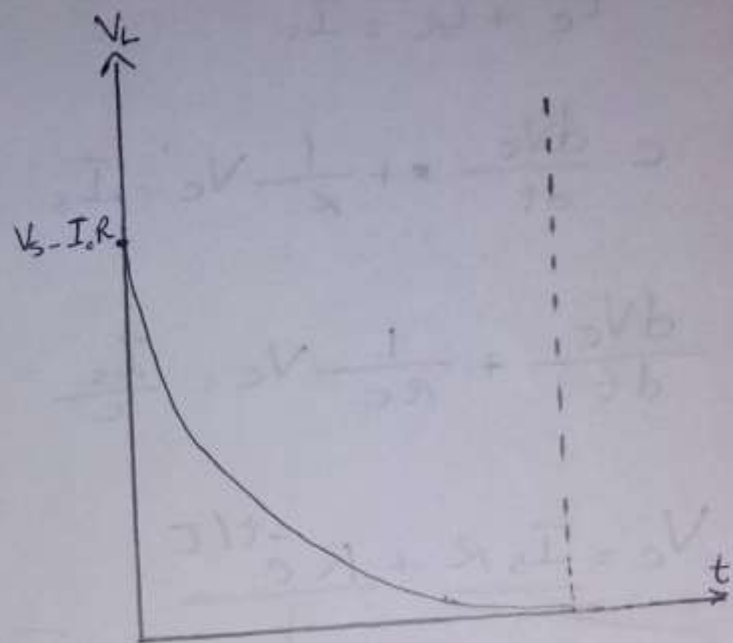
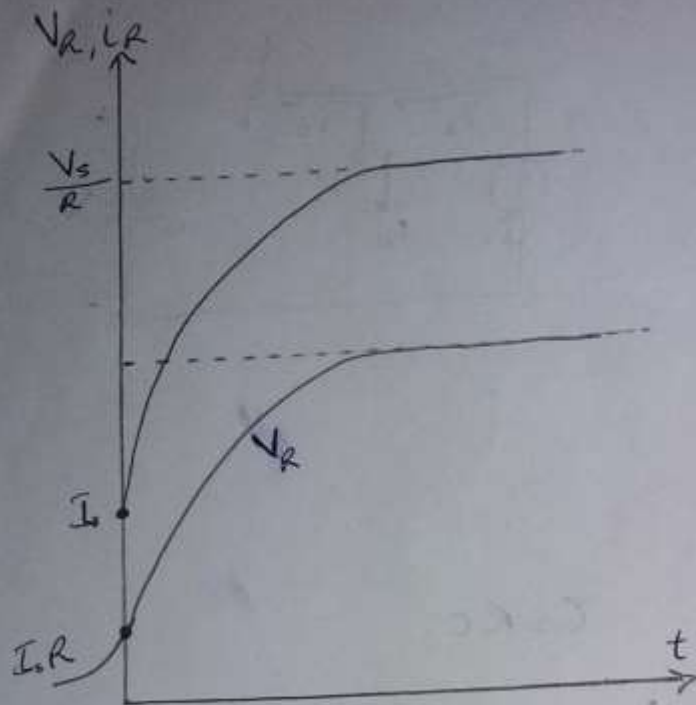
$$i(t) = \frac{V_s}{R} + \left( I_0 - \frac{V_s}{R} \right) e^{-t/\tau}$$

$$\tau = \frac{L}{R}$$

$$\text{if } I_0 = 0 \Rightarrow i(t) = \frac{V_s}{R} (1 - e^{-t/\tau})$$

$$V_L = L \frac{di}{dt} = (V_s - I_0 R) e^{-t/\tau}$$

$$V_R = V_s + (I_0 R - V_s) e^{-t/\tau}$$



Another case

$$i = \frac{V_s - V_L}{R}$$

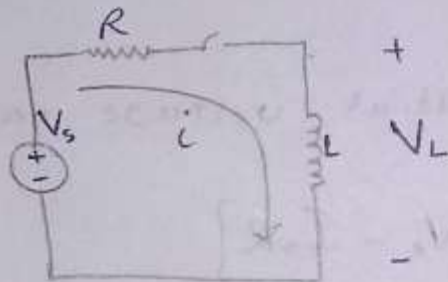
$$\frac{di}{dt} = \frac{-1}{R} \frac{dV_L}{dt}$$

$$L \frac{di}{dt} = \frac{-L}{R} \frac{dV_L}{dt}$$

$$V_L = \frac{-L}{R} \frac{dV_L}{dt}$$

$$V_L(0) = V_s - I_0 R$$

$$\therefore V_L = K e^{-t/\tau}$$





# step Response of an RC circuit

$$i_c + i_R = I_s$$

$$C \frac{dV_c}{dt} + \frac{1}{R} V_c = I_s$$

$$\frac{dV_c}{dt} + \frac{1}{RC} V_c = \frac{I_s}{C}$$

$$V_c = \underbrace{I_s R}_{\text{(steady state)}} + \underbrace{K e^{-t/\tau}}_{\text{(transient)}}$$

$$\tau = RC$$

\* using initial voltage on capacitor ( $V_0$ ) [is considered]

$$K = [V_0 - I_s R]$$

$$V_c = I_s R + (V_0 - I_s R) e^{-t/\tau}$$

$$t \rightarrow \infty \rightarrow *$$

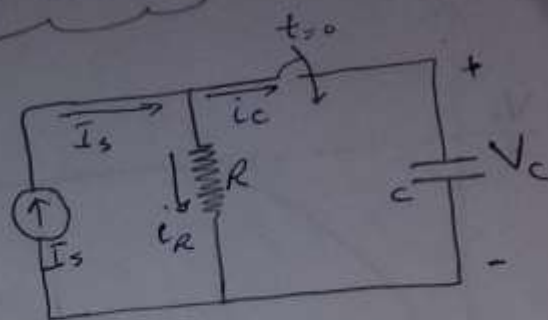
For zero I.C (Initial condition)

$$V_c = I_s R (1 - e^{-t/\tau})$$

$$i_c = C \frac{dV_c}{dt} \quad (\text{general case})$$

$$i_c = \left( I_s - \frac{V_0}{R} \right) e^{-t/\tau}$$

$$t \rightarrow 0^+$$



$$V_c + i_c R = (I_s - i_c) R$$

$$\frac{dV_c}{dt} = -R \frac{di_c}{dt} \quad * c$$

$$c \frac{dV_c}{dt} = -Rc \frac{di_c}{dt}$$

$$i_c = -Rc \frac{di_c}{dt}$$

$$\frac{di_c}{dt} + \frac{1}{Rc} i_c = 0$$

From \* we can get General Form.

$$A(t) = A(\infty) + [A(0^+) - A(\infty)] e^{-t/\tau}$$

General solution

$$\frac{dx}{dt} + \frac{1}{\tau} x = K$$

$$x(t=t_0) = x_0$$

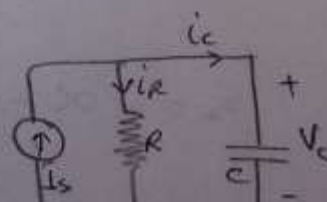
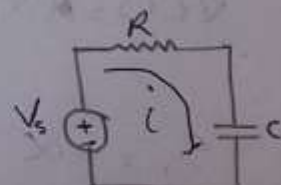
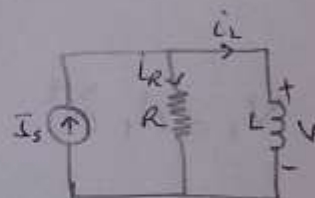
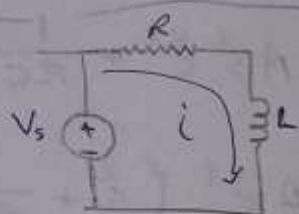
$$x = x_{ss} + x_t$$

$$x_{ss} : \frac{dx}{dt} = 0 \Rightarrow x_{ss} = K\tau$$

$$x_t = A e^{-(t-t_0)/\tau} = K\tau + A e^{-(t-t_0)/\tau}$$

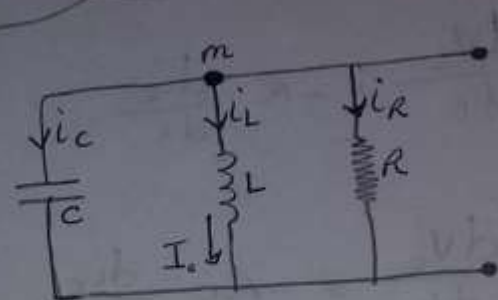
$$x(t) = x_f + (x_0 - x_f) e^{-(t-t_0)/\tau}$$

we need :



قوة الجهد للدارع  
معادلات الحالة

# Natural response of Parallel RLC



at  $t=0$

$$i_R + i_L + i_C + \bar{I}_0 = 0$$

$$\frac{V}{R} + \frac{1}{L} \int V dt + C \frac{dV}{dt} + \bar{I}_0 = 0$$

$$\frac{1}{R} \frac{dV}{dt} + \frac{V}{L} + C \frac{d^2 V}{dt^2} = 0$$

$$\boxed{\frac{d^2 V}{dt^2} + \frac{1}{RC} \frac{dV}{dt} + \frac{1}{LC} V = 0}$$

$$V = A e^{st}, \quad \frac{dV}{dt} = A s e^{st}, \quad \frac{d^2 V}{dt^2} = A s^2 e^{st}$$

$$A s^2 e^{st} + \frac{1}{RC} A s e^{st} + \frac{1}{LC} A e^{st} = 0$$

$$A e^{st} \left( s^2 + \frac{1}{RC} s + \frac{1}{LC} \right) = 0$$

$$V_1 = A_1 e^{s_1 t}, \quad V_2 = A_2 e^{s_2 t}$$

$$V(t) = V_1 + V_2 = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$

$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

بأجراء القاطع بالنسبة لـ

$$V(0) = V_0, \quad i_L(0) = \bar{I}_0$$



where:

$$\alpha = \frac{1}{2RC} \rightarrow \text{reference frequency}$$

$$\omega_0 = \frac{1}{\sqrt{LC}} \rightarrow \text{resonance frequency}$$

rad/sec

①  $\alpha > \omega_0 \rightarrow$  "over damped"

( $s_1, s_2$  real and distinct)

$$V(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

②  $\alpha < \omega_0 \rightarrow$  "under damped"

( $s_1, s_2$  complex and conjugated)

$$V(t) = e^{-\alpha t} (B_1 \cos(\omega_d t) + B_2 \sin(\omega_d t))$$

where:  $\omega_d = \sqrt{\omega_0^2 - \alpha^2} \rightarrow$  damped radian frequency

③  $\alpha = \omega_0 \rightarrow$  "critically damped"

( $s_1, s_2$  real and equal)

$$V(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$$

① over damped response (proof) ( $\alpha > \omega_0$ )

$$V(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$A_1, A_2 \rightarrow$  initial condition,  $V_0(0^+) \rightarrow$  initial voltage of capacitor.

$$\frac{dV}{dt}(0^+) = \frac{i_C(0^+)}{C} = \frac{-i_L(0^+) - i_R(0^+)}{C} = \frac{-i_L(0^+) - \frac{V(0^+)}{R}}{C}$$

$$\frac{dV}{dt}(0^+) = A_1 s_1 + A_2 s_2$$

$$V(0^+) = A_1 + A_2$$

② critically damped

$$\alpha = \omega_0$$

$$s_1 = s_2 = -\alpha = \frac{-1}{2RC}$$

$$V(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$$

$$V(0^+) = D_2$$

$$\frac{dV}{dt}(0^+) = D_1 - \alpha D_2$$

③ under damped ( $\alpha < \omega_0$ )

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$= -\alpha \pm j\sqrt{\omega_0^2 - \alpha^2} = -\alpha \pm j\omega_d$$

where:  $\omega_d = \sqrt{\omega_0^2 - \alpha^2} \rightarrow$  damped radian frequency

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} = A_1 e^{(-\alpha + j\omega_d)t} + A_2 e^{(-\alpha - j\omega_d)t}$$

$$= A_1 e^{-\alpha t} e^{j\omega_d t} + A_2 e^{-\alpha t} e^{-j\omega_d t}$$

$$\frac{\pm j\theta}{e^{\pm j\theta}} = \cos \theta \pm j \sin \theta$$

$$v(t) = A_1 e^{-\alpha t} (\cos(\omega_d t) + j \sin(\omega_d t)) + A_2 e^{-\alpha t} (\cos(\omega_d t) - j \sin(\omega_d t))$$

$$v(t) = e^{-\alpha t} \left[ \underbrace{(A_1 + A_2)}_{B_1} \cos(\omega_d t) + \underbrace{j(A_1 - A_2)}_{B_2} \sin(\omega_d t) \right]$$

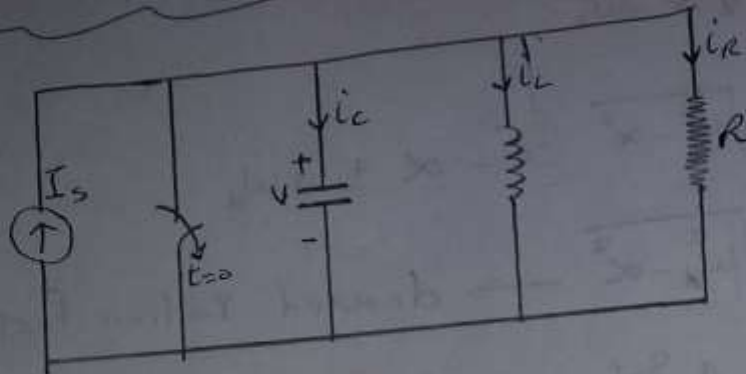
$$v(t) = e^{-\alpha t} [B_1 \cos(\omega_d t) + B_2 \sin(\omega_d t)]$$

$$v(0^+) = B_1$$

$$\frac{dv}{dt}(0^+) = -\alpha B_1 + \omega_d B_2$$



# step response of Parallel RLC



At  $t=0$

Apply KCL

$$I_s = i_C + i_R + i_L$$

\* يا جرد الا مشغول  
بالنسبة ل  $t$

$$I_s = C \frac{dv}{dt} + \frac{v}{R} + \frac{1}{L} \int v dt + I_0$$

$$0 = \frac{C d^2 v}{dt^2} + \frac{v}{L} + \frac{1}{R} \frac{dv}{dt} = 0$$

$$\frac{d^2 v}{dt^2} + \frac{1}{LC} v + \frac{1}{RC} \frac{dv}{dt} = 0$$

$$v = A e^{st}, \quad \frac{dv}{dt} = A s e^{st}, \quad \frac{d^2 v}{dt^2} = A s^2 e^{st}$$

$$A e^{st} \left( s^2 + \frac{1}{RC} s + \frac{1}{LC} \right) = 0$$

$$s_{1,2} = \frac{-1}{2RC} \pm \sqrt{\left( \frac{1}{2RC} \right)^2 - \frac{1}{LC}}$$

$$-\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

and

①  $\alpha > \omega_0 \rightarrow$  over damped  $\Rightarrow V(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$

②  $\alpha < \omega_0 \rightarrow$  under damped  $\Rightarrow V(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$

③  $\alpha = \omega_0 \rightarrow$  critically  $\Rightarrow V(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$

$$i_L(t) = I_s + \begin{cases} A_1 e^{s_1 t} + A_2 e^{s_2 t} \rightarrow \text{over damped} \\ (B_1 \cos(\omega_d t) + B_2 \sin(\omega_d t)) e^{-\alpha t} \rightarrow \text{under damped} \\ D_1 t e^{-\alpha t} + D_2 e^{-\alpha t} \rightarrow \text{critically damped} \end{cases}$$

$$i_L(t) = \frac{V(t)}{R} = \underbrace{\frac{A_1}{R} e^{s_1 t}}_{A'_1} + \underbrace{\frac{A_2}{R} e^{s_2 t}}_{A'_2} + 0$$

General Form

$$A(t) = A(\infty) + \begin{cases} A_1 e^{s_1 t} + A_2 e^{s_2 t} \\ e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t) \\ D_1 t e^{-\alpha t} + D_2 e^{-\alpha t} \end{cases}$$

$$i_L(t) = I_f + A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$i_L(0^+) = I_f + A_1 + A_2$$

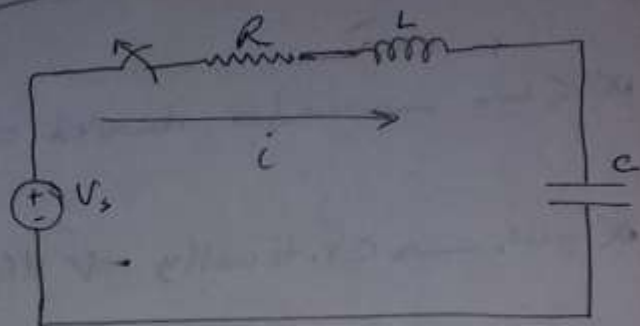
$$\frac{di_L(0^+)}{dt} = \frac{V_L(0^+)}{L}, A_1 s_1 + A_2 s_2$$

$$i_L(\infty) = I_f$$

$$V_L(\infty) = 0$$

$$i_L = \frac{1}{L} \int_0^t v(t) dt + I_0$$

# Natural and ~~step~~ response of series RLC circuits



At  $t=0$

$$V_R + V_L + V_C = 0$$

$$iR + L \frac{di}{dt} + \frac{1}{C} \int_0^t i dt + V_s = 0$$

$$L \frac{d^2 i}{dt^2} + \frac{i}{C} + \frac{R di}{dt} = 0$$

$$\boxed{\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0}$$

$$i = A e^{st}, \quad \frac{di}{dt} = A s e^{st}, \quad \frac{d^2 i}{dt^2} = A s^2 e^{st}$$

$$A s^2 e^{st} + \frac{R}{L} A s e^{st} + \frac{1}{LC} A e^{st} = 0$$

$$A e^{st} \left( s^2 + \frac{R}{L} s + \frac{1}{LC} \right) = 0$$

→ ch/s

$$s_{1,2} = \frac{-R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega^2}$$



$$\alpha = \frac{R}{2L}, \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

$$\alpha > \omega_0 \rightarrow \text{over} \Rightarrow i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$\alpha < \omega_0 \rightarrow \text{under} \Rightarrow i(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

$$\alpha = \omega_0 \rightarrow \text{critically} \Rightarrow i(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$$

$$V_L = L \frac{di}{dt}, \quad V_C = \frac{1}{C} \int_0^t i dt + V_0, \quad V_R = iR$$

Step response of series RLC

$$V_s = V_R + V_L + V_C$$

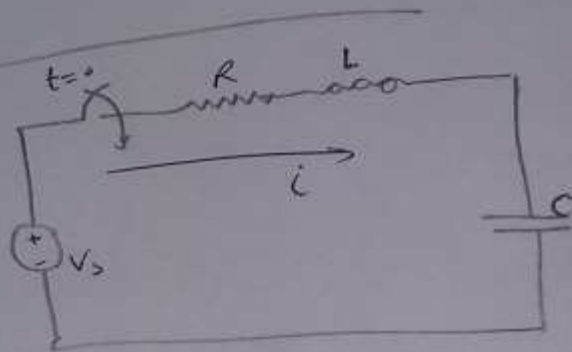
$$V_s = iR + L \frac{di}{dt} + \frac{1}{C} \int_0^t i dt + V_0$$

$$0 = \frac{L d^2 i}{dt^2} + R \frac{di}{dt} + \frac{i}{C} = 0$$

$$\boxed{\frac{d^2 i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{1}{LC} i = 0}$$

وبعد ذلك نفس الخطوات  
Natural

$$i(t) = A_f + \begin{cases} A_1 e^{s_1 t} + A_2 e^{s_2 t} \\ B_1 e^{-\alpha t} \cos \omega_d t + B_2 e^{-\alpha t} \sin \omega_d t \\ D_1 t e^{-\alpha t} + D_2 e^{-\alpha t} \end{cases}$$



# **Ch : 3**

## **3-phase**

Ch: 3

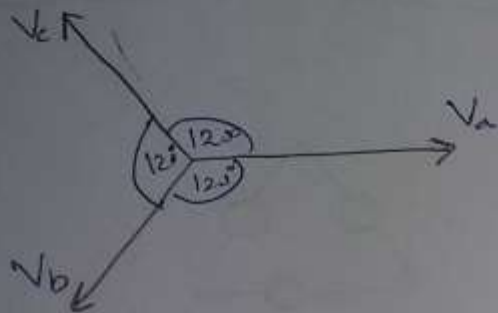
## Three Phase Circuits

### Balanced three phase voltages

\* عبارة عن ثلاثة جهد لهم نفس ال magnitude وبينهم phase shift  $120^\circ$

⇒ +ve sequence (abc)

$V_a$  عن  $\begin{cases} 120^\circ \text{ متأخر ب } V_b \\ 120^\circ \text{ متقدم ب } V_c \end{cases}$



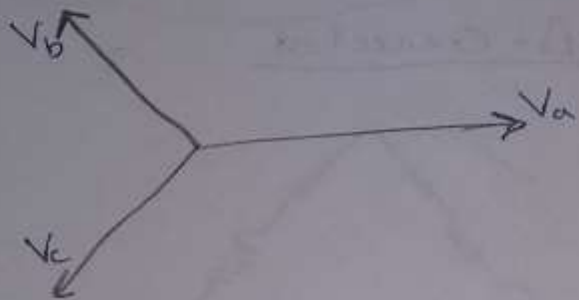
$$V_a = |V_\phi| \angle 0^\circ$$

$$V_b = |V_\phi| \angle -120^\circ$$

$$V_c = |V_\phi| \angle 120^\circ$$

⇒ -ve sequence (acb)

$V_a$  عن  $\begin{cases} 120^\circ \text{ متقدم ب } V_b \\ 120^\circ \text{ متأخر ب } V_c \end{cases}$



$$V_a = |V_\phi| \angle 0^\circ$$

$$V_b = |V_\phi| \angle 120^\circ$$

$$V_c = |V_\phi| \angle -120^\circ$$

شروط ال Balanced

① نفس ال magnitude - ② بينهم phase shift  $120^\circ$  ③  $V_a + V_b + V_c = 0$

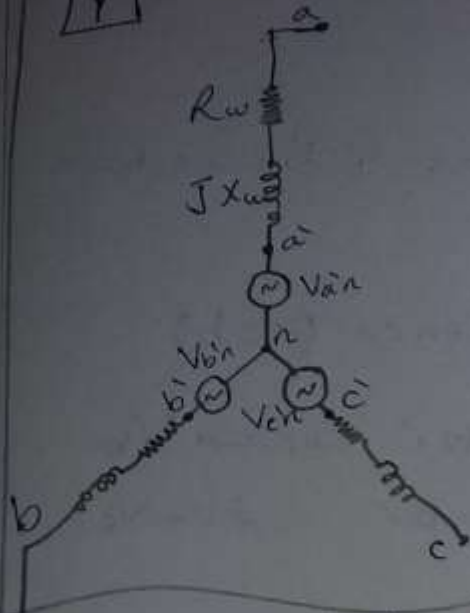
\* 3  $\phi$  - voltage source

1 Y-Connected.

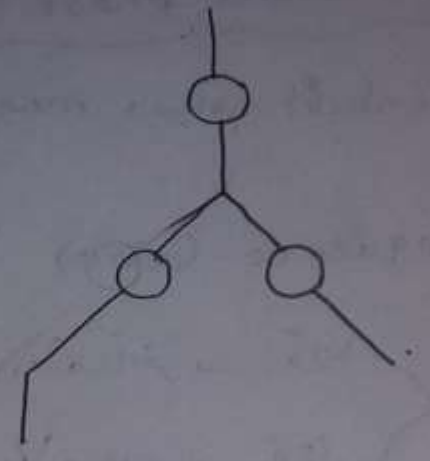
2  $\Delta$ -Connected.



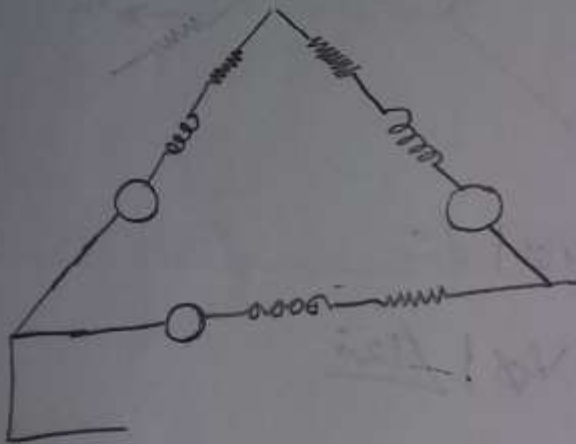
**Y**



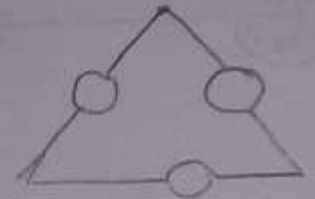
ideal →



**Δ - Connected**



ideal →



\* They are:

Source → load

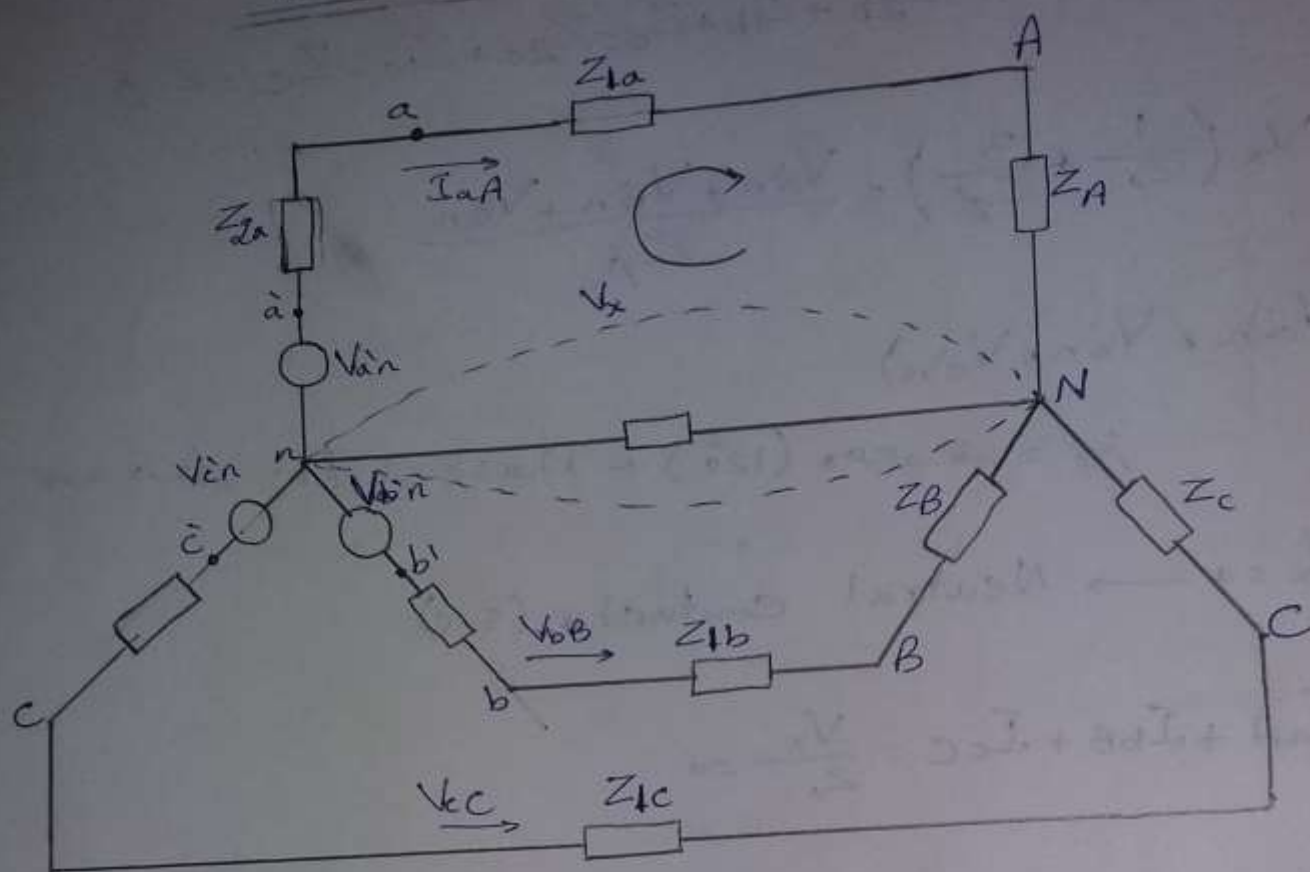
① Y - Y

② Y - Δ

③ Δ - Y

④ Δ - Δ

## Y-Y Connected



$$I_s = I_{aA} + I_{bB} + I_{cC}$$

$$= \frac{V_{an} - V_x}{Z_{sa} + Z_{La} + Z_A} + \frac{V_{bn} - V_x}{Z_{sb} + Z_{Lb} + Z_B} + \frac{V_{cn} - V_x}{Z_{sc} + Z_{Lc} + Z_C}$$

For balanced system:

$$V_a = V_b = V_c = 0$$

$$Z_{sa} = Z_{sb} = Z_{sc}$$

$$Z_A = Z_B = Z_C$$

$$Z_{La} = Z_{Lb} = Z_{Lc}$$

$$Z_{2a} + Z_{1a} + Z_A = Z_{2b} + Z_{1b} + Z_B = Z_{2c} + Z_{1c} + Z_C = Z_\phi$$

$$V_x \left( \frac{1}{Z_0} + \frac{3}{Z_\phi} \right) = \frac{V_{an} + V_{bn} + V_{cn}}{Z_\phi}$$

( $V_{an}$ ,  $V_{bn}$ ,  $V_{cn}$ )

فلا تفرق بين  $V_{an}$  و  $V_{bn}$  و  $V_{cn}$   $(120^\circ)$  ← Phase shift  
و  $V_{an}$  و  $V_{bn}$  و  $V_{cn}$  = فرق

$V_x = 0 \rightarrow$  Neutral conductor (s.c)

$$I_a A + I_b B + I_c C = \frac{V_x}{Z_0} = 0$$

$\therefore$  Currents are also balanced.

if  $\rightarrow$  +ve sequence

$$V_{AN} = 2 \angle 15^\circ$$

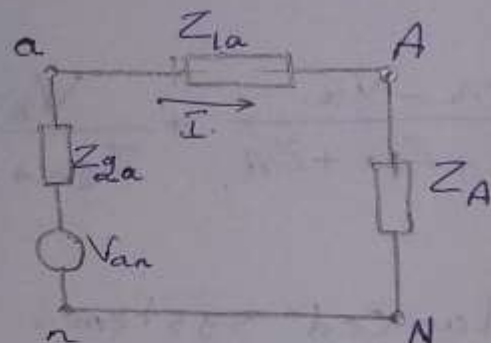
$$V_{BN} = 2 \angle -105^\circ$$

$$V_{CN} = 2 \angle 135^\circ$$

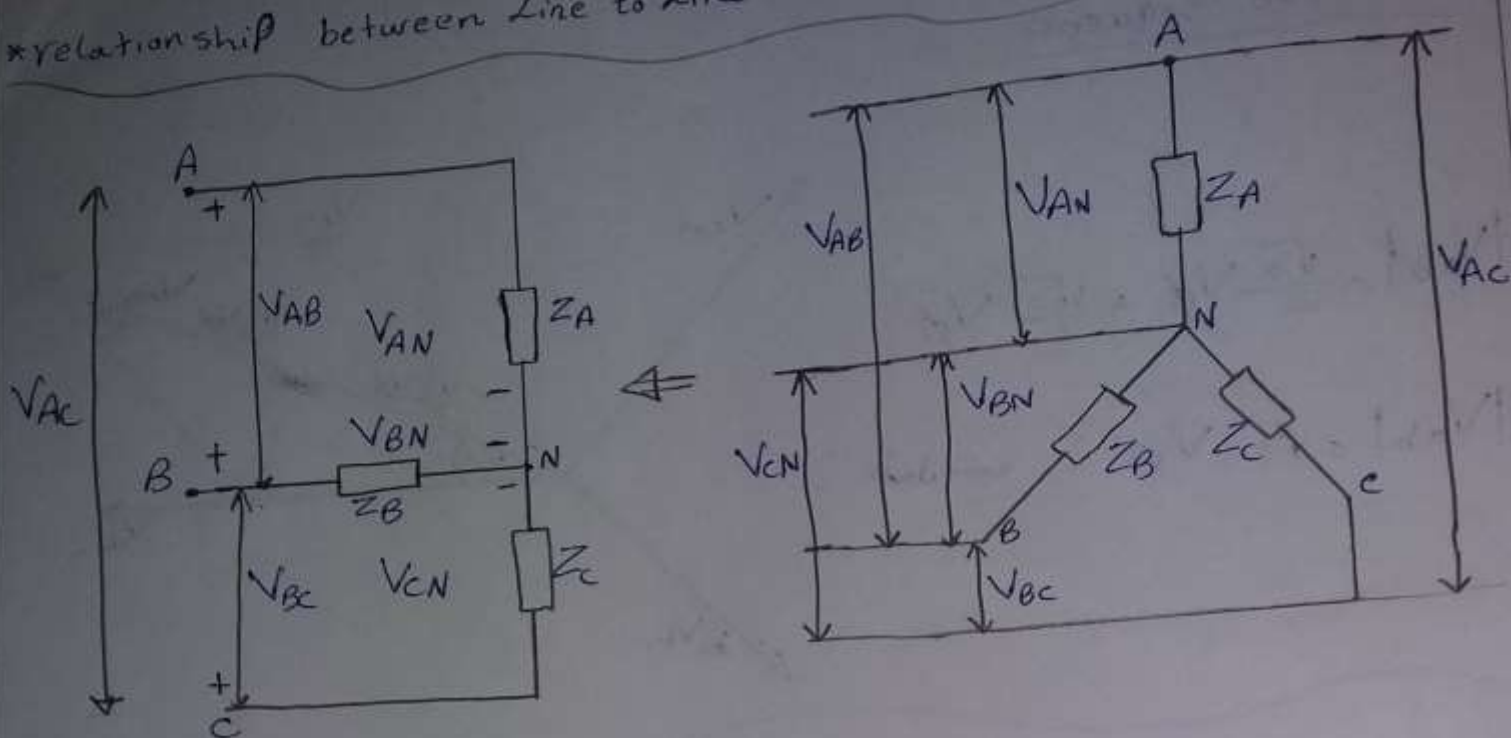
if  $\rightarrow$  -ve sequence

$$V_{AN} = 2 \angle 15^\circ$$

$$V_{BN} = 2 \angle 135^\circ$$



\*relationship between Line to Line voltages and Phase voltages:



$$V_{AB} - V_{AN} + V_{BN} = 0$$

$$V_{AB} = V_{AN} - V_{BN}$$

$$V_{BC} = V_{BN} - V_{CN}$$

$$V_{CA} = V_{CN} - V_{AN}$$

$$V_{AB} = V_{AN} - V_{BN} = V_{\phi} \angle 0^\circ - V_{\phi} \angle -120^\circ$$

$$V_{AB} = \sqrt{3} V_{\phi} \angle +30^\circ \rightarrow \text{For +ve sequence.}$$

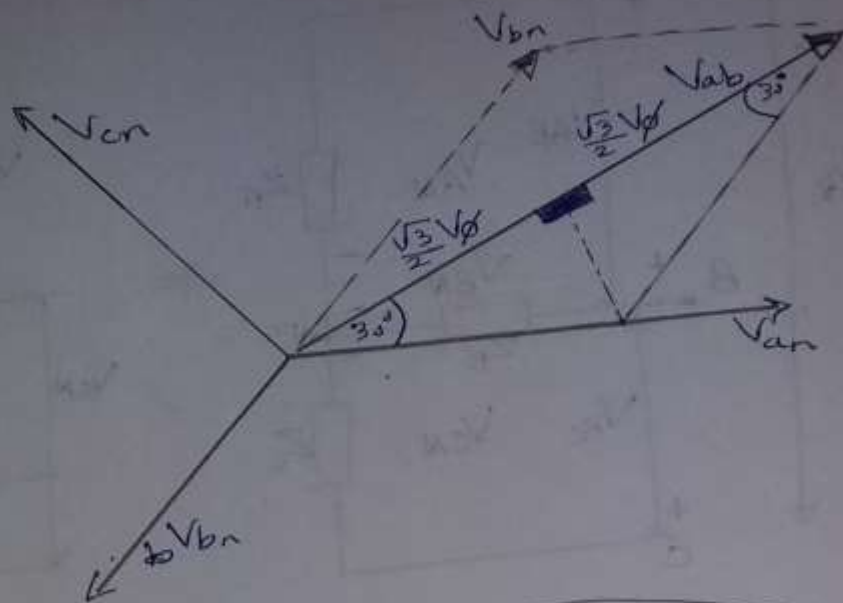
$$V_{AB} = \sqrt{3} V_{\phi} \angle -30^\circ \rightarrow \text{For -ve sequence.}$$



for +ve sequence

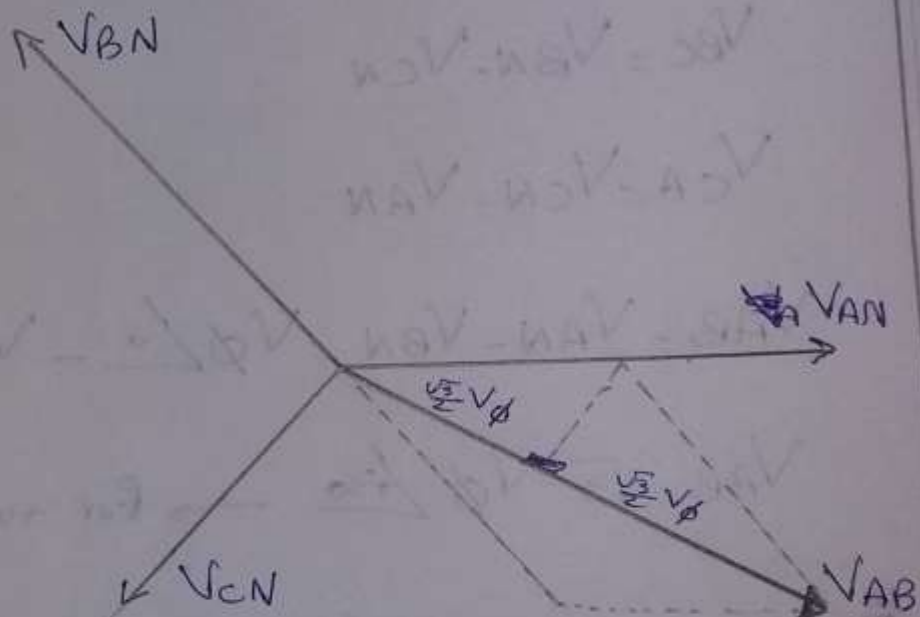
$$|V_{ab}| = \frac{\sqrt{3}}{2} V_{\phi} + \frac{\sqrt{3}}{2} V_{\phi}$$

$$|N_{ab}| = \sqrt{3} V_{\phi}$$



-ve sequence

$$|V_{AB}| = \sqrt{3} V_{\phi}$$



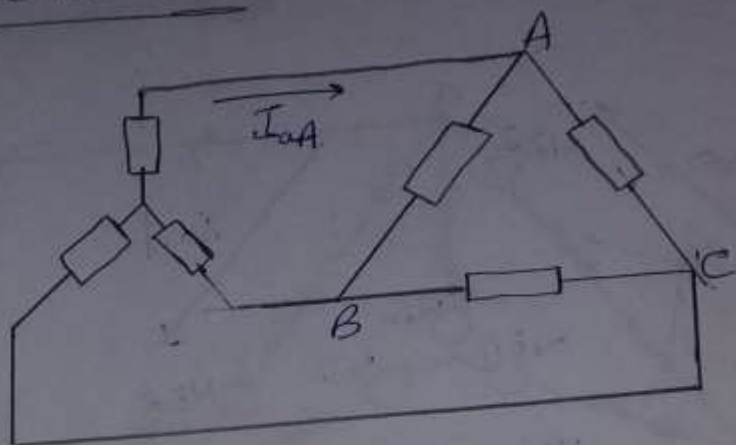
$V_{AN}$ :

$$V_{AB} = \sqrt{3} V_{AN} \angle +30^{\circ} \rightarrow +ve$$

$$V_{AB} = \sqrt{3} V_{AN} \angle -30^{\circ} \rightarrow -ve$$

## 2] Y-Δ Connected

$$Z_Y = \frac{Z_\Delta}{3}$$



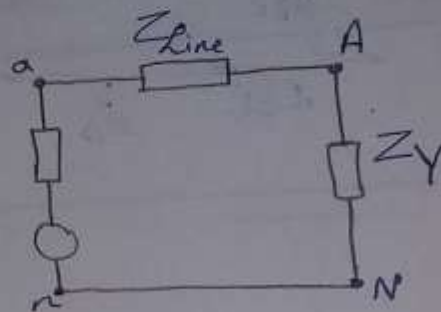
Δ

$$I_L \neq I_\phi$$

$$V_L = V_\phi$$

Y

$$I_L = I_\phi, \quad V_L \neq V_\phi$$



\*Phase voltage at terminals of load ( $V_{AB}, V_{BC}, V_{CA}$ )

Apply Kcl at node A

$$I_{LA} = I_{AB} - I_{CA}$$

$$= I_\phi \angle 0^\circ - I_\phi \angle 120^\circ$$

$$I_{LA} = \sqrt{3} I_\phi \angle -30^\circ$$

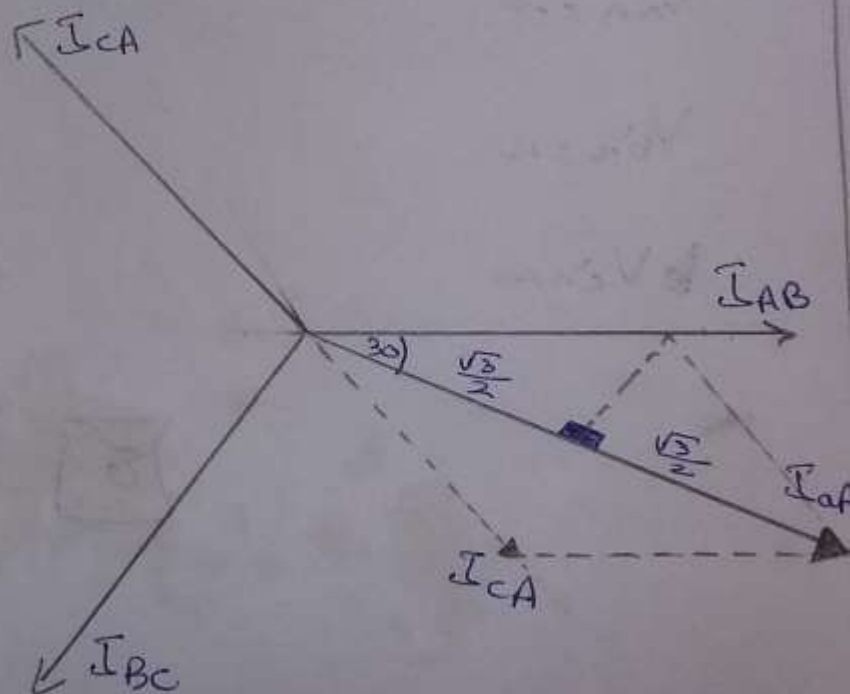
→ line current

→ true seq.

$$I_{AB} = I_\phi \angle 0^\circ$$

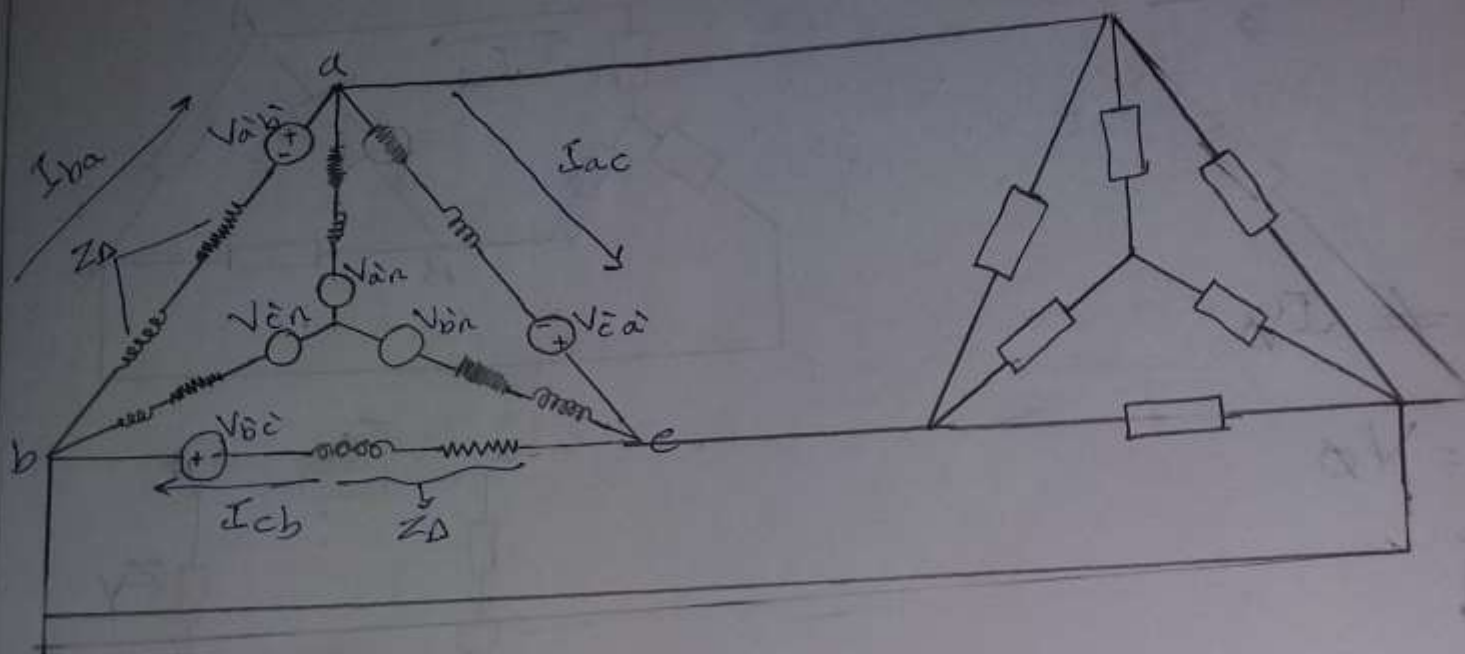
$$I_{BC} = I_\phi \angle -120^\circ$$

$$I_{CA} = I_\phi \angle 120^\circ$$



7

### 3 $\Delta/Y$ Connected



$$Z_Y = \frac{Z_{\Delta}}{3}$$

$$V_{ab} = \sqrt{3} V_{an} \angle \pm 30^\circ$$

$$V_{an} = v$$

$$V_{bn} = v$$

$$V_{cn} = v$$

## Power in circuits

For Y-load

$$P_A = |V_{AN}| |I_{aA}| \cos(\theta_v - \theta_i)$$

$$P_B = |V_{BN}| |I_{bB}| \cos(\theta_v - \theta_i)$$

$$P_C = |V_{CN}| |I_{cC}| \cos(\theta_v - \theta_i)$$

For balanced system

$$|V_{AN}| = |V_{BN}| = |V_{CN}| = V_\phi$$

$$|I_{aA}| = |I_{bB}| = |I_{cC}| = I_\phi$$

$$(\theta_v - \theta_i)_A = (\theta_v - \theta_i)_B = (\theta_v - \theta_i)_C = \theta_\phi$$

$$P_A = P_B = P_C = V_\phi I_\phi \cos \theta_\phi$$

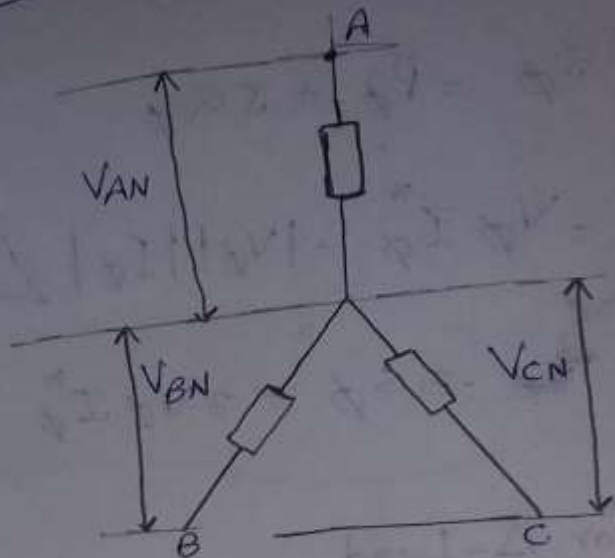
$$P_{3\phi} = P_A + P_B + P_C = 3V_\phi I_\phi \cos \theta_\phi$$

$$= \sqrt{3} \frac{\sqrt{3}}{\sqrt{3}} V_L I_L \cos \theta_\phi = \sqrt{3} V_L I_L \cos \theta_\phi$$

\* Reactive power (Q)

$$Q_A = Q_B = Q_C = V_\phi I_\phi \sin \theta_\phi$$

$$Q_{3\phi} = 3V_\phi I_\phi \sin \theta_\phi = \sqrt{3} V_L I_L \sin \theta_\phi \quad \text{VAR}$$





### \* Apparent Power (s)

$$S_{\phi} = P_{\phi} \pm jQ_{\phi}$$

$$+ \rightarrow \text{Lag} (Q_L > Q_C)$$

$$\rightarrow \text{Lead} (Q_L < Q_C)$$

$$= V_{\phi} I_{\phi}^* = |V_{\phi}| |I_{\phi}| \angle \pm \theta_i \quad \text{VA}$$

$$S_{3\phi} = 3 S_{\phi} = 3 V_{\phi} I_{\phi}^*$$

### For $\Delta$ -Load

$$P_{AB} = |V_{AB}| |I_{AB}| \cos(\theta_v - \theta_i)_{AB}$$

$$P_{BC} = |V_{BC}| |I_{BC}| \cos(\theta_v - \theta_i)_{BC}$$

$$P_{CA} = |V_{CA}| |I_{CA}| \cos(\theta_v - \theta_i)_{CA}$$

$$|V_{AB}| = |V_{BC}| = |V_{CA}| = V_{\phi}$$

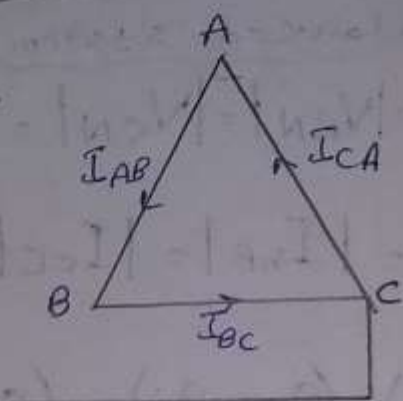
$$|I_{AB}| = |I_{BC}| = |I_{CA}| = I_{\phi}$$

$$(\theta_v - \theta_i)_{AB} = (\theta_v - \theta_i)_{BC} = (\theta_v - \theta_i)_{CA} = \theta_{\phi}$$

$$P_{AB} = P_{BC} = P_{CA} = P_{\phi} = V_{\phi} I_{\phi} \cos \theta_{\phi}$$

$$P_{3\phi} = 3 P_{\phi} = 3 V_{\phi} I_{\phi} \cos \theta_{\phi}$$

$$= \sqrt{3} V_L I_L \cos \theta_{\phi}$$



### \* Reactive Power (Q)

$$Q_{AB} = Q_{BC} = Q_{CA} = Q_{\phi} = V_{\phi} I_{\phi} \sin \theta_{\phi}$$

$$Q_{3\phi} = 3V_{\phi} I_{\phi} \sin \theta_{\phi} = \sqrt{3} V_L I_L \sin \theta_{\phi}$$

### \* Apparent Power (S)

$$S_{\phi} = P_{\phi} + jQ_{\phi}$$

$$S_{3\phi} = P_{3\phi} + jQ_{3\phi}$$

ملحوظة: Power في الفيزياء  
تكون (Power) في  
الفيزياء على (3) .

نها!

### \* Instantaneous Power

$$P_A(t) = V_{AN}(t) \cdot I_{aA}(t) = V_m \cos(\omega t) \cdot I_m \cos(\omega t - \theta_{\phi})$$

$$P_B(t) = V_m I_m \cos(\omega t - 120) \cos(\omega t - 120 - \theta_{\phi})$$

$$P_C(t) = V_m I_m \cos(\omega t + 120) \cos(\omega t + 120 - \theta_{\phi})$$

$$P_{3\phi}(t) = P_A + P_B + P_C = 1.5 V_m I_m \cos(\theta_{\phi})$$

↳ time invariant

torque  $\leftarrow T = \frac{P}{\omega} \rightarrow$  time invariant

$$= 3 \left( \frac{V_m}{\sqrt{2}} \right) \left( \frac{I_m}{\sqrt{2}} \right) \cos \theta_{\phi} = 3 V_{\phi} I_{\phi} \cos \theta_{\phi}$$

$$P_{3\phi} = \sqrt{3} V_L I_L \cos \theta_{\phi}$$

**Ch : 4**

# **Mutual inductance**

Ch: 4

## Mutual inductance

تسمى بـ  $\lambda$  (المغناطيسية)  $\lambda \rightarrow$  Flux linkage

$$V = \frac{d\lambda}{dt}$$

$$\lambda = N\phi$$

$$\phi = \frac{\lambda}{N}$$

$\mu \rightarrow$  Permeance

مساحة أي وسط المجال في لشغل خطوط الفيض المغناطيسي  $\mu \rightarrow$

Magnetic materials

$$\mu \propto \phi$$

nonmagnetic

$$\mu \rightarrow \text{Constant } (\phi \propto i)$$

$$V = \frac{d\lambda}{dt} = \frac{d}{dt}(N^2 \mu i) = N^2 \mu \frac{di}{dt}$$

$$V = L \frac{di}{dt}$$

$L \rightarrow$  self inductance

$$L = N^2 \mu$$

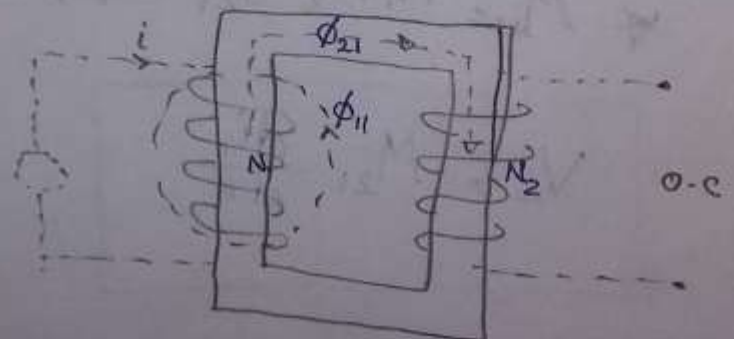
## Mutual inductance (M)

هي ال Parameter التي يربط الجهد المتحث على الملفين بالتيار المار بالمكثف الآخر.

$$\phi_1 = \phi_{11} + \phi_{21} = N_1 \mu_1 i_1$$

$$\phi_{11} = \mu_{11} N_1 i_1$$

$$\phi_{21} = \mu_{21} N_1 i_1$$





$$V_1 = \frac{d\lambda_1}{dt}$$

$$\lambda_1 = N_1 \phi_1 = N_1 (\phi_{11} + \phi_{21})$$

$$\lambda_1 = N_1 (\mu_{11} N_1 i_1 + \mu_{21} N_1 i_1)$$

$$\lambda_1 = N_1^2 \mu_{11} i_1$$

$$V_1 = N_1^2 \mu_{11} \frac{di_1}{dt} = L_1 \frac{di_1}{dt}$$

\* للجهد المتولد على الملف  $N_2$  نتيجة مرور التيار فيها  $\Leftarrow$

$$V_2 = \frac{d\lambda_2}{dt} = N_2 \frac{d\phi_{21}}{dt}$$

$$\lambda_2 = N_2 \phi_{21}$$

$$\phi_{21} = \mu_{21} N_1 i_1$$

$$\lambda_2 = N_1 N_2 \mu_{21} i_1$$

$$V_2 = \frac{d}{dt} (N_1 N_2 \mu_{21} i_1)$$

$$V_2 = N_1 N_2 \mu_{21} \frac{di_1}{dt}$$

$$\nRightarrow M_{21} = N_1 N_2 \mu_{21} \Rightarrow \text{Mutual Inductance (H)}$$

$$V_2 = M_{21} \frac{di_1}{dt}$$

$$V_2 = N_2 \int_2 \frac{di_2}{dt}$$

$$V_2 = L_2 \frac{di_2}{dt}$$

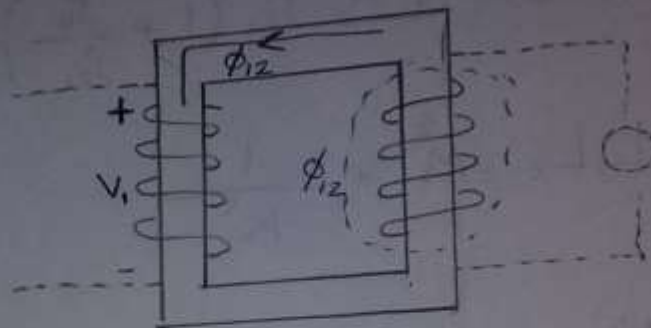
$$V_1 = N_1 N_2 \int_{12} \frac{di_2}{dt}$$

$$V_1 = M_{12} \frac{di_2}{dt}$$

$$M_{21} = N_1 N_2 \int_{21} \quad \therefore M_{12} = N_1 N_2 \int_{12}$$

$$\therefore \int_{21} = \int_{12}$$

$$\therefore M_{21} = M_{12} = M$$



\*relationship between  $L_1, L_2, M$

$$L_1 = N_1^2 \int_1^2 = N_1^2 (\int_{11} + \int_{21})$$

$$L_2 = N_2^2 \int_2^2 = N_2^2 (\int_{22} + \int_{12})$$

$$L_1 L_2 = N_1^2 N_2^2 (\int_{11} + \int_{21}) (\int_{12} + \int_{22})$$

$$L_1 L_2 = N_1^2 N_2^2 \frac{\Phi_{21}^2}{\Phi_{21}} \left(1 + \frac{\Phi_{11}}{\Phi_{21}}\right) \left(1 + \frac{\Phi_{22}}{\Phi_{21}}\right)$$

$$L_1 L_2 = M^2 \times \frac{1}{K^2}$$

$K \rightarrow$  Mutually Coupling.

$$0 \leq K \leq 1$$

$$M^2 = L_1 L_2 K^2$$

$$M = K \sqrt{L_1 L_2}$$

1) if  $K = 0$

$\therefore M = 0$  لا يوجد دمج بين الملفين

2) if  $K = 1$

$$M = \sqrt{L_1 L_2}$$

\* أي أن كل الفيض القادم يستحول إلى  $\Phi_{21}$

ملحوظة

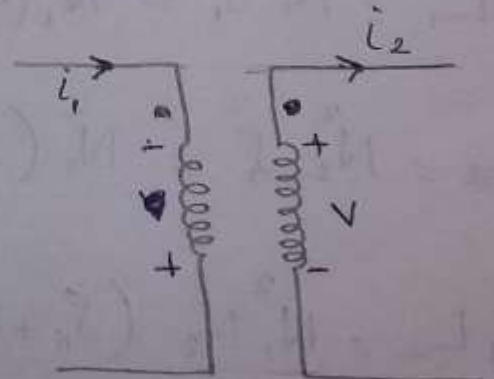
\* أي ملفين يكون بينهما ربط (Coupling) يتفاعل كل منهما (Mutual voltage)

\* يتم تحديد الـ (Polarity) ↓ (Mutual voltage) بواسطة Dot marking.

\* إذا كان التيار  $i_1$  داخل (Dot) بتاعة الملف

فالـ (Polarity) تكون على الملف الآخر (+) والعكس

يحدث مع  $i_2$ .







sheet 4

1] Two magnetically coupled coils have self-inductance of 52 mH and 13 mH, respectively. The Mutual Inductance between the coils is 19.5 mH

- a) What is the coefficient of coupling?  
b) For these two coils, what is the largest value that M can have.  
c) ~~The physical construction of four pairs of magnetically coupled coils is shown~~  
d) Assume that the physical structure of these coupled coils is such that  $\phi_1 = \phi_2$  what is the turn ratio  $\frac{N_1}{N_2}$ ?

Solution

$$L_1 = 52 \text{ mH}, L_2 = 13 \text{ mH}, M = 19.5 \text{ mH}$$

$$a) K = \frac{M}{\sqrt{L_1 L_2}} = \frac{19.5 \times 10^{-3}}{\sqrt{52 \times 13 \times 10^{-6}}} = 0.75$$

$$b) \text{ at } K = 1 \\ M_{\max} = \sqrt{L_1 L_2} = 26 \text{ mH}$$

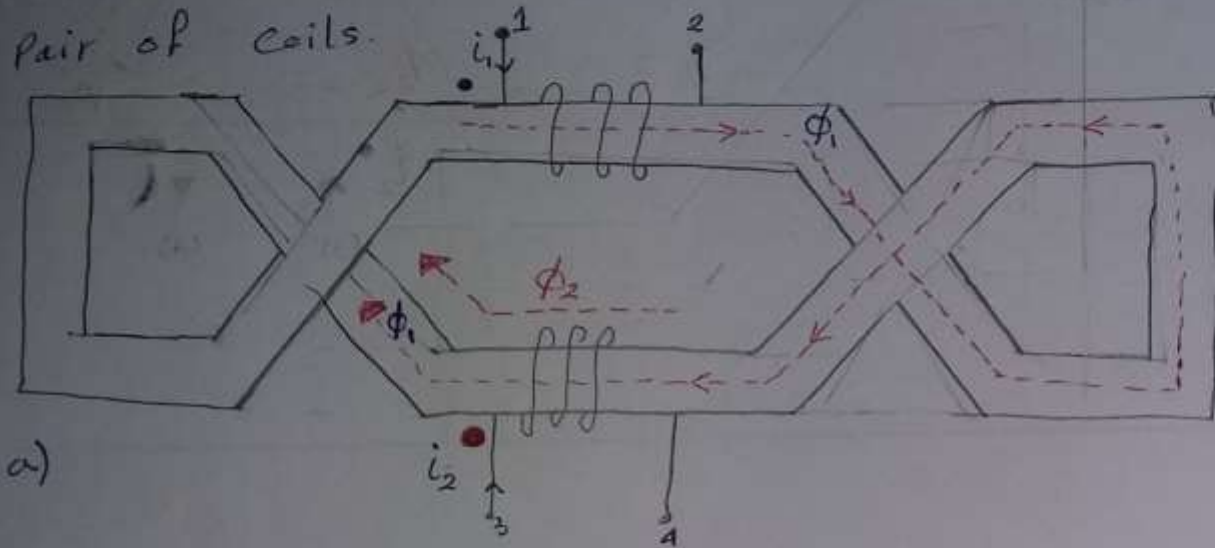
$$c) \phi_1 = \phi_2$$

$$L_1 = N_1^2 \phi_1^2 = 52, \quad L_2 = N_2^2 \phi_2^2 = 13$$

$$\frac{52}{13} = \frac{N_1^2}{N_2^2} = \frac{4}{1}$$

$$\therefore \frac{N_1}{N_2} = \frac{2}{1}$$

2] The physical construction of four pairs of magnetically coupled coils is shown in Fig. 1. Assume the magnetic flux is confined to the core material in each structure. show the possible locations for the dot markings on each pair of coils.



~~نضع (dot) عند مكان دخول التيار عند (1)~~

نضع (dot) عند مكان دخول التيار عند (1).

نلاحظ أن  $\phi_1$  و  $\phi_2$  في نفس الاتجاه.

نضع (Dot) عند (3) مكان دخول التيار.

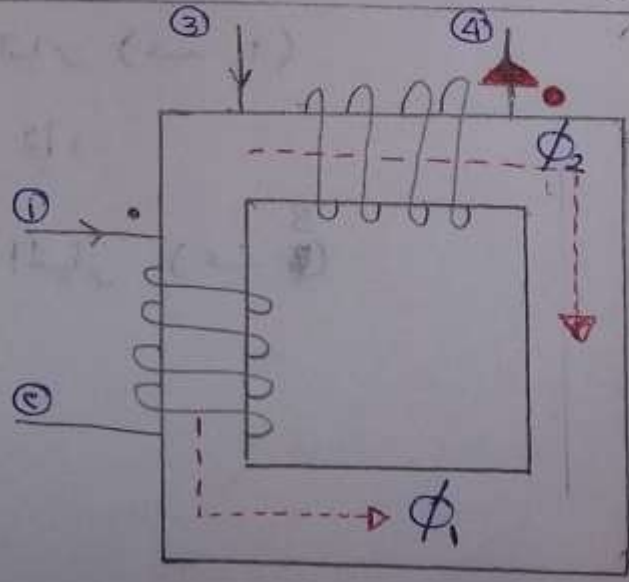
b)

نضع (Dot) عند مكان دخول التيار

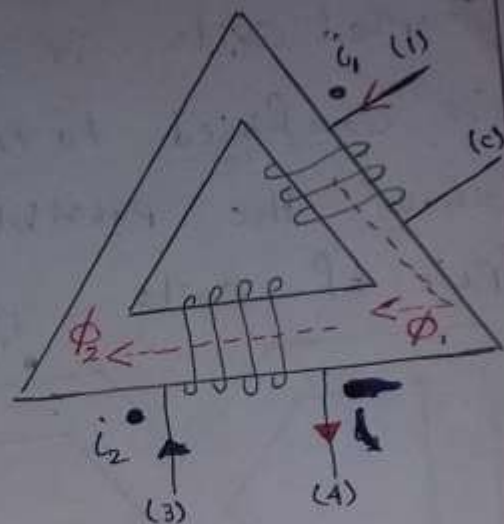
نلاحظ أن  $\phi_1$  و  $\phi_2$  في اتجاهين متعاكسين.

نضع الـ (Dot) عند مكان خروج

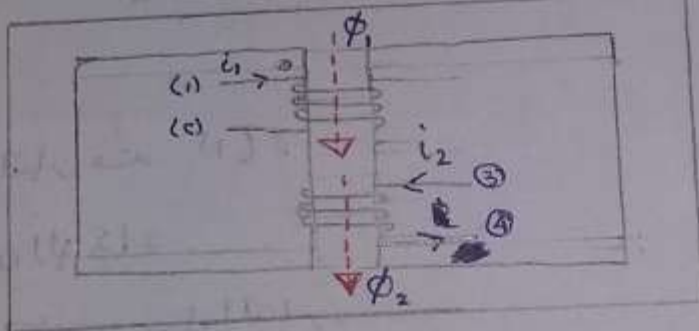
التيار عند (4).



- (c) (a) نفخ (Dot) عند مكان دخول التيار عند (1)  
 (b) فلاحظ أن  $\phi_1$  ،  $\phi_2$  في نفس الاتجاه .  
 (c) نفخ (Dot) عند مكان ~~دخول~~ التيار عند (3) <sup>3</sup>



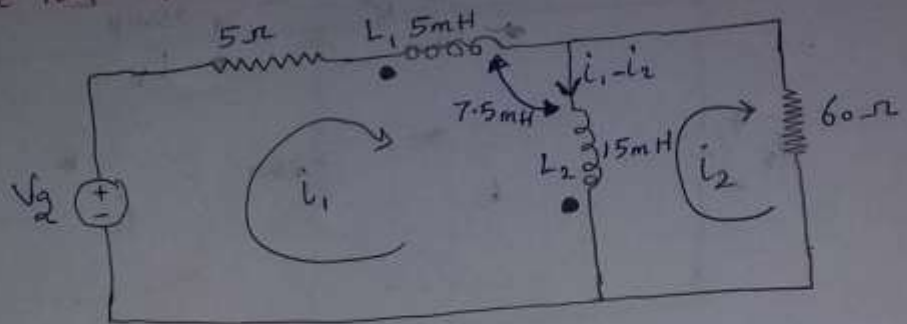
[d]



- (a) نفخ (Dot) عند مكان دخول التيار عند (1)  
 (b) فلاحظ أن  $\phi_1$  ،  $\phi_2$  في نفس الاتجاه .  
 (c) نفخ (Dot) عند مكان ~~دخول~~ التيار عند (3) <sup>3</sup>

\* Write down the loop equations for the following circuits.

a)



\* نفرض أن  $i_1$  أكبر من  $i_2$  فيكون التيار  $(i_1 - i_2)$  خارج من (Dot) فتكون  
 الـ (Polarity) على  $L_1$  (- +)  

$$\frac{M d(i_1 - i_2)}{dt}$$
  
 \* لو  $i_2 > i_1$  ← التياران لهما اتجاه داخل الـ (Dot) فيكون الـ (Polarity) على  $L_1$  (+ -)  

$$-\frac{M d(i_1 - i_2)}{dt}$$
  
 وذلك ثابتة.

Equations

For Loop ①

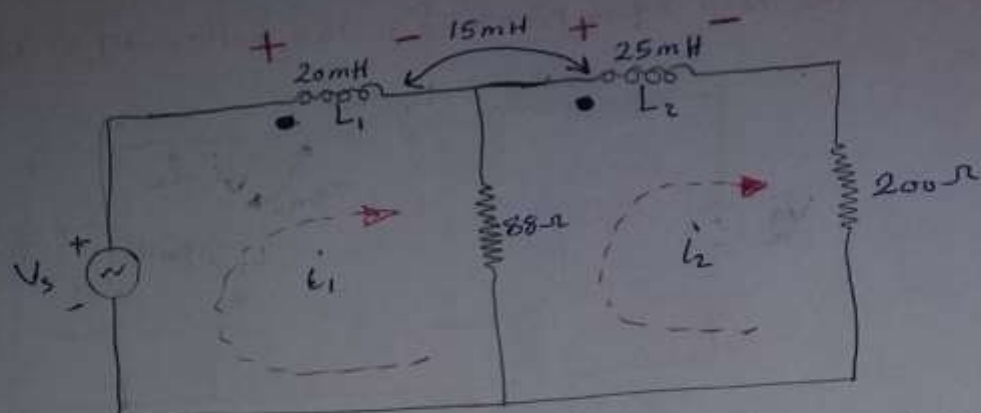
$$V_g - 5i_1 - L_1 \frac{di_1}{dt} - M \frac{d(i_1 - i_2)}{dt} - L_2 \frac{d(i_1 - i_2)}{dt} + M \frac{di_1}{dt} = 0$$

For Loop ②

$$-L_2 \frac{d(i_2 - i_1)}{dt} - M \frac{di_1}{dt} - 50i_2 = 0$$



b)



\* التيار  $i_1$  داخل للـ (Dot) فتكون الـ (Polarity)  $(+ -) L_2$  وبالمثل مع  $(+ -) L_1$

### Equations

$$V_s = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt} + 88(i_1 - i_2)$$

### For Loop (1)

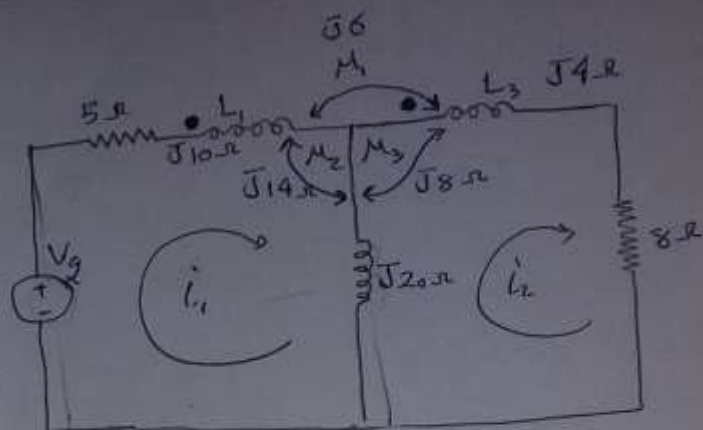
$$V_s - L_1 \frac{di_1}{dt} - M \frac{di_2}{dt} - 88(i_1 - i_2) = 0$$

### For Loop (2)

$$-88(i_2 - i_1) - L_2 \frac{di_2}{dt} - M \frac{di_1}{dt} - 200i_2 = 0$$

c)

ملحوظة: لو أعطى ملفات لا يوجد عليها (Dot) ولا ( $\rightarrow$ ) فهو (Self Inductance).



\*  $i_1$  داخل على (Dot) فيفساً على

$$L_2 \rightarrow M_2 \frac{di_1}{dt}, L_3 \rightarrow M_3 \frac{di_1}{dt}$$

\*  $(i_1 - i_2)$  للـ  $i_2$  بسبب

$$L_1 \rightarrow M_2 \frac{d(i_1 - i_2)}{dt} (+ -), L_3 \rightarrow M_3 \frac{d(i_1 - i_2)}{dt} (+ -)$$

\*  $i_2$  داخل  $\rightarrow$  Dot

$$L_1 \rightarrow M_1 \frac{di_2}{dt}, L_2 \rightarrow M_3 \frac{di_2}{dt}$$

For Loop (1)

$$V_g - 5i_1 - L_1 \frac{di_1}{dt} - M_1 \frac{di_2}{dt} - M_2 \frac{d(i_1 - i_2)}{dt} - L_2 \frac{d(i_1 - i_2)}{dt}$$

$$-M_3 \frac{di_2}{dt} - M_2 \frac{di_1}{dt} = 0$$

For Loop (2)

$$-L_2 \frac{d(i_2 - i_1)}{dt} + M_2 \frac{di_1}{dt} + M_3 \frac{di_2}{dt} - L_3 \frac{di_2}{dt}$$

$$-M_1 \frac{di_1}{dt} - M_3 \frac{d(i_1 - i_2)}{dt} - 8i_2 = 0$$

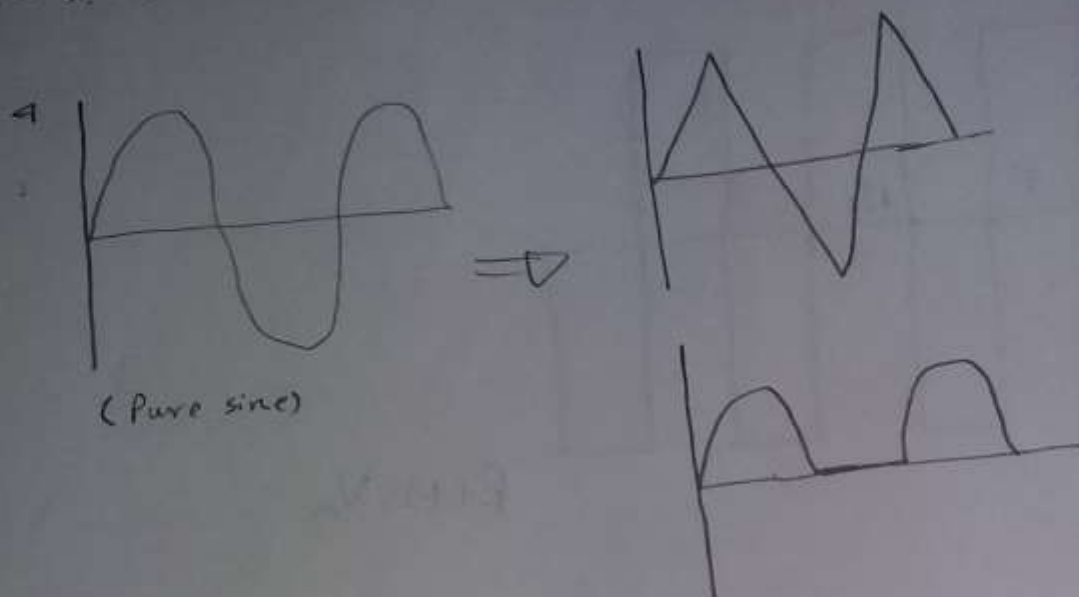
# **Ch:5**

## **Fourier**

Ch: 5

# Fourier series

\* أي مصدر (Ac) يقوم بإخراج إشارة (Pure sine) ولدي نسب وجود شوائب تؤثر على الموجة.



موج غير sinusoidal and Periodic (Non sinusoidal and Periodic)  
 أي صيغة رياضية يمكن كتابتها على شكل مجموع من sine, cosine

$$f(t) = a_v + \sum_{n=1}^{\infty} a_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)$$

angular frequency

$\omega_0$  → Frequency of  $a_v, a_n, b_n$  Fourier harmonic coefficients.  
 $2\omega_0$  → Frequency of  $b$

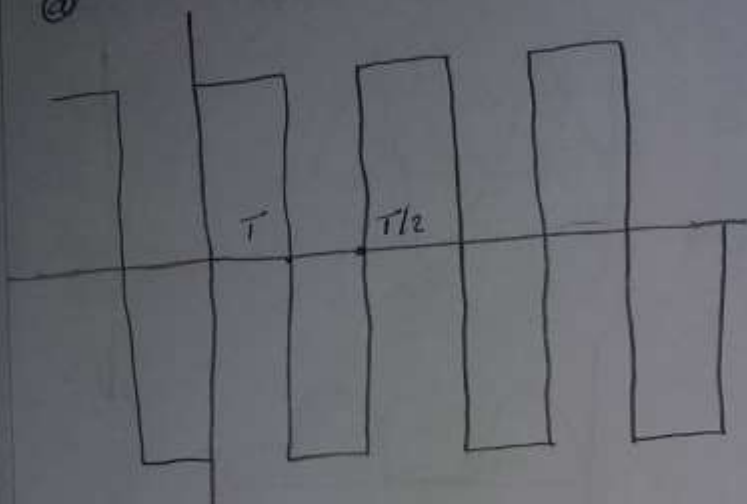
$$a_v = \frac{1}{T} \int_{t_1}^{t_1+T} f(t) dt \quad , \quad b_n = \frac{2}{T} \int_{t_1}^{t_1+T} f(t) \sin(n\omega_0 t) dt$$

$$a_n = \frac{2}{T} \int_{t_1}^{t_1+T} f(t) \cos(n\omega_0 t) dt$$



1

2



$$f(t) = V_m$$

$$a_0 = 0, a_n = 0$$

$$b_n = \frac{4}{T} \int_0^{T/2} f(t) \sin(n\omega_0 t) dt$$

$$= \frac{4}{T} \int_0^{T/2} V_m \sin(n\omega_0 t) dt$$

$$= \frac{4V_m}{T} \left[ \frac{-\cos(n\omega_0 t)}{n\omega_0} \right]_0^{T/2}$$

$$\omega_0 = \frac{2\pi}{T}$$

$$= \frac{4V_m}{nT \frac{2\pi}{T}} \left[ -\cos\left(n \frac{2\pi}{T} * \frac{T}{2}\right) + 1 \right]$$

$$b_n = \frac{4V_m}{n\pi}$$

$$f(t) = \sum_{n=1}^{\infty} b_n \sin n\omega_0 t$$

$$= \sum_{n=1}^{\infty} \frac{4V_m}{n\pi} \sin(n\omega_0 t)$$

$$= \frac{4V_m}{\pi} \sin\omega_0 t + \frac{4V_m}{3\pi} \sin 3\omega_0 t + \dots$$

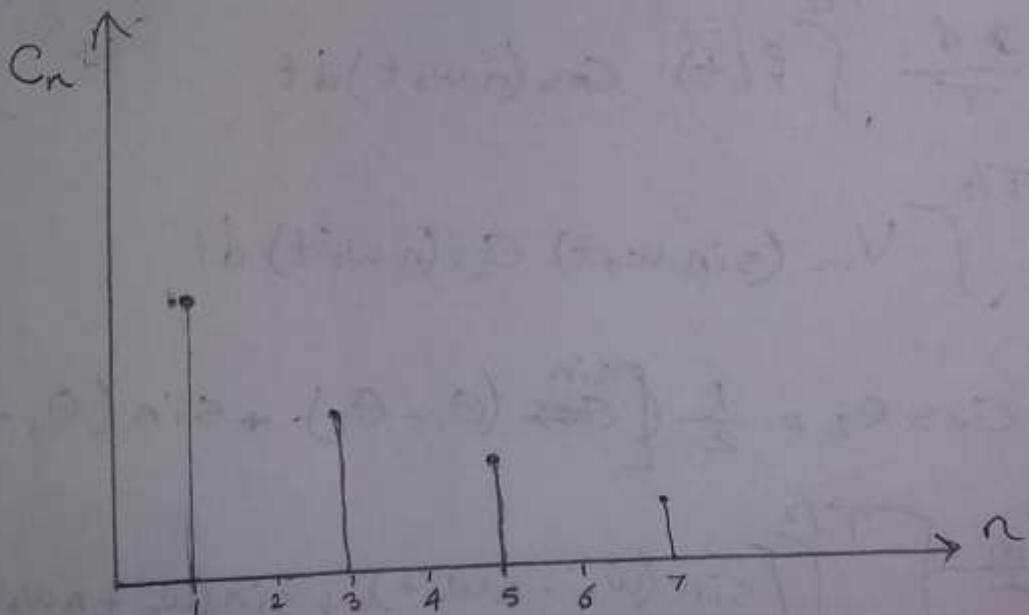
→ spectrum

$$C_n = \sqrt{a_n^2 + b_n^2} \quad (C_0 = a_0)$$

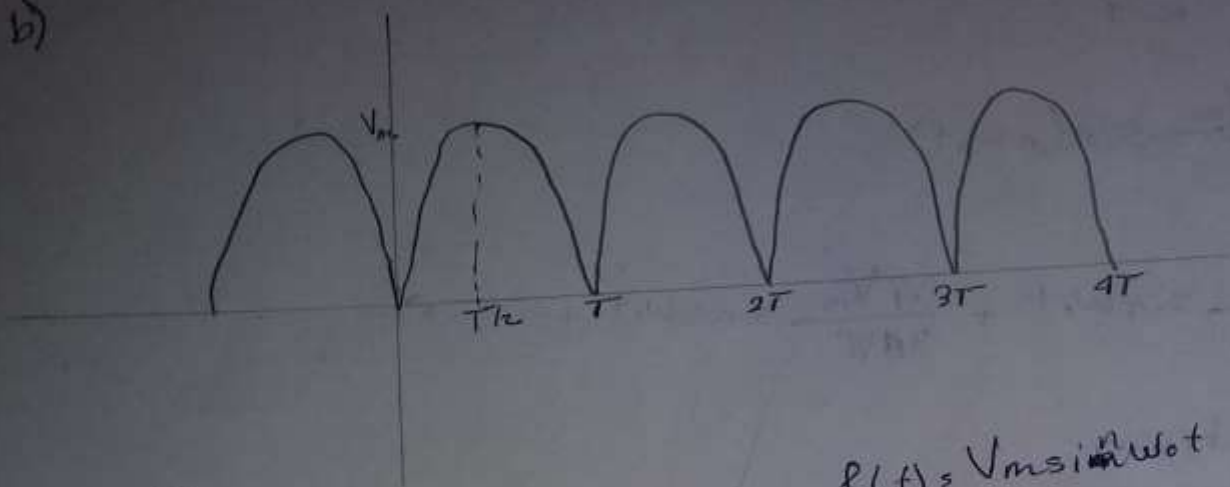
$$C_1 = \sqrt{a_1^2 + b_1^2} = \frac{4V_m}{\pi}$$

$$C_2 = \sqrt{a_2^2 + b_2^2} = 0$$

$$C_3 = \sqrt{a_3^2 + b_3^2} = \frac{4V_m}{3\pi}$$



b)



$$f(t) = V_m \sin n\omega_0 t$$

even function

$$a_0, a_n, \boxed{b_n = 0}$$

$$a_0 = \frac{2}{T} \int_0^{T/2} f(t) dt = \frac{2}{T} \int_0^{T/2} V_m \sin(n\omega_0 t) dt$$

$$= \frac{2V_m}{T} \left[ -\frac{\cos(n\omega_0 t)}{n\omega_0} \right]_0^{T/2} = \frac{2V_m}{T}$$

$$a_n = \frac{2}{T} \int_0^{T/2} f(t) \cos(n\omega_0 t) dt$$

$$= \frac{2}{T} \int_0^{T/2} V_m (\sin \omega_0 t) \cos(n\omega_0 t) dt$$

$$\sin \theta_1 \cos \theta_2 = \frac{1}{2} [\sin(\theta_1 - \theta_2) + \sin(\theta_1 + \theta_2)]$$

$$= \frac{2V_m}{T} \int_0^{T/2} [\sin(\omega_0 - n\omega_0 t) + \sin(\omega_0 + n\omega_0 t)] dt$$

$$= \frac{2V_m}{T} \left[ -\frac{\cos(\omega_0 - n\omega_0 t)}{\omega_0(1-n)} - \frac{\cos(\omega_0 + n\omega_0 t)}{\omega_0(1+n)} \right]_0^{T/2}$$

$$= \frac{2V_m}{T \times \frac{2\pi}{T}} \left[ \frac{-\cos(1-n)\frac{2\pi}{T} \frac{T}{2}}{1-n} - \frac{\cos(1+n)\frac{2\pi}{T} \frac{T}{2}}{1+n} + \frac{1}{1-n} + \frac{1}{1+n} \right]$$

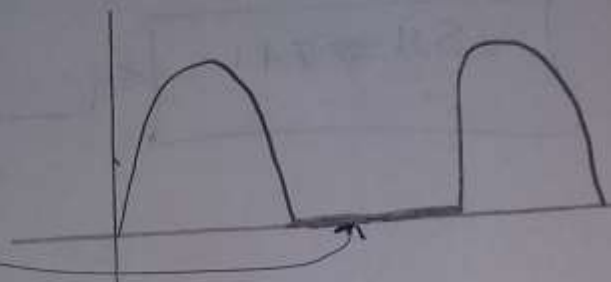
$$= \frac{4V_m/\pi}{1-4n^2}$$

[3]

$$a_v = \frac{1}{T} \int_0^{T/2} V_m \sin \omega_0 t \, dt + 0$$

$$a_n = \frac{1}{T} \int_0^{T/2} V_m \sin \omega_0 t \cos(n\omega_0 t) \, dt + 0$$

$$b_n = \frac{1}{T} \int_0^{T/2} V_m \sin \omega_0 t \sin(n\omega_0 t) \, dt + 0$$





**Ch:6**

# **Operational amplifier**

ch: 6

# operational amplifier

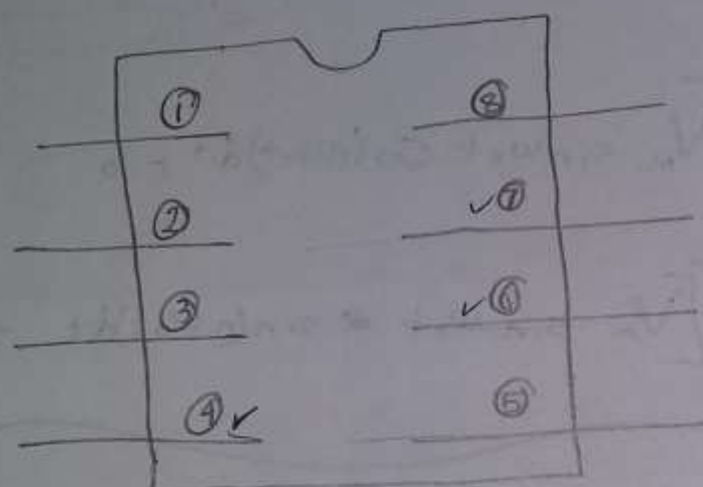
\* عبارة عن دوائر متكاملة تستخدم في عمليات معينة مثل الجمع والطرح...

\* From analogue computer

دوائر متكاملة دوائر بها مقادير ومقاييس وعلاقات مرتبطة مع بعضها تستخدم في عمليات.

\* يكوّن طرفان "أ" و "ب" و "ج" و "د"

741 = الكود



② → inverting input

③ → non inverting input

④ → -ve supply

⑦ → +ve supply

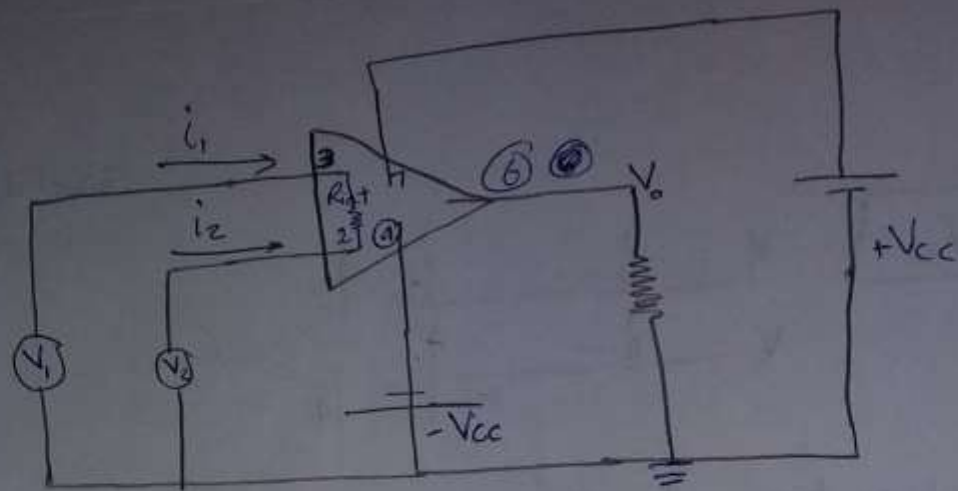
⑤ not connected

①, ⑥ → null offset

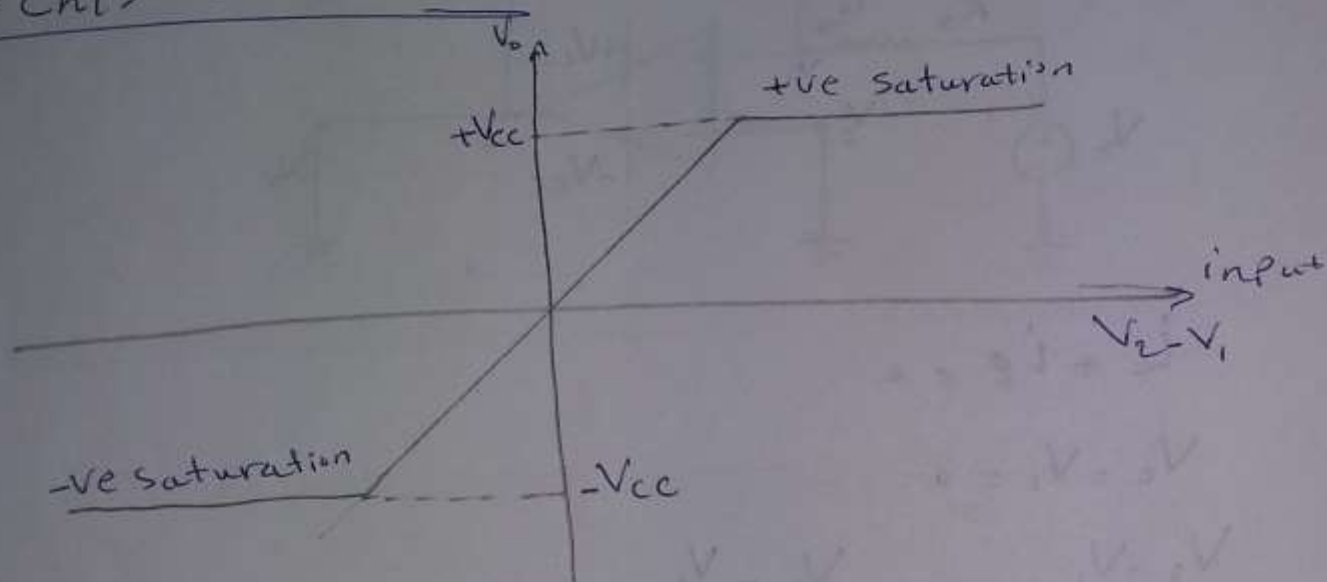
⑦ out put

لو عندى موجة مثل عادية فاقزير  
فى حد معين تستخدم offset





\* chls of amp.



$$V_o = A(V_2 - V_1)$$

$A \rightarrow$  gain

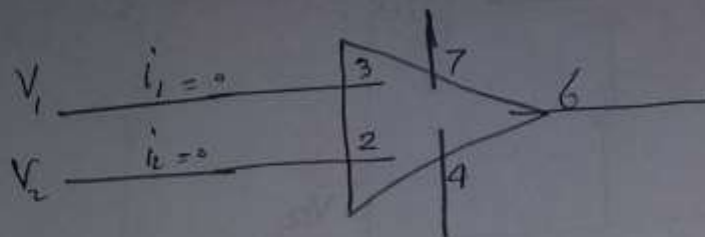
at ideal  $\Rightarrow A_v \rightarrow$  very large  $\approx \infty$

$$\therefore \frac{V_2 - V_1}{1} = \frac{V_o}{A \uparrow}$$

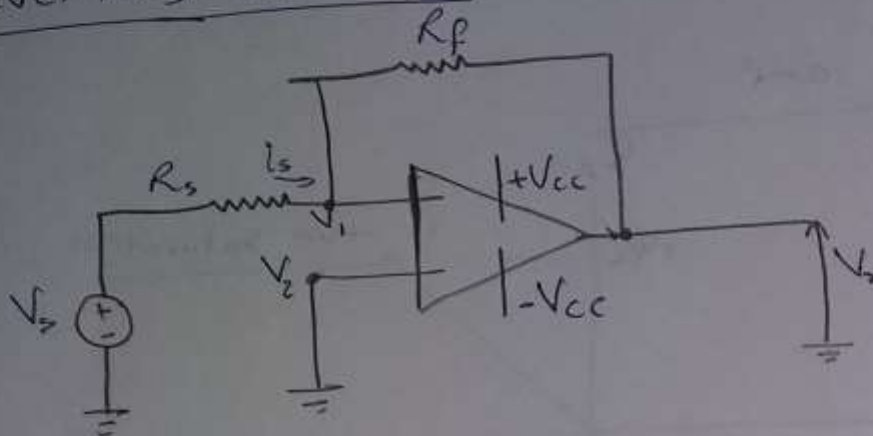
$$\therefore V_2 - V_1 \approx 0$$

$$\therefore \boxed{V_2 = V_1}$$

$$V_1 = V_2$$



## 1] Inverting Amplifier



$$i_s + i_f = 0$$

$$V_2 = V_1 = 0$$

$$\frac{V_s - V_1}{R_s} + \frac{V_o - V_1}{R_f} = 0$$

$$\frac{V_s}{R_s} = -\frac{V_o}{R_f}$$

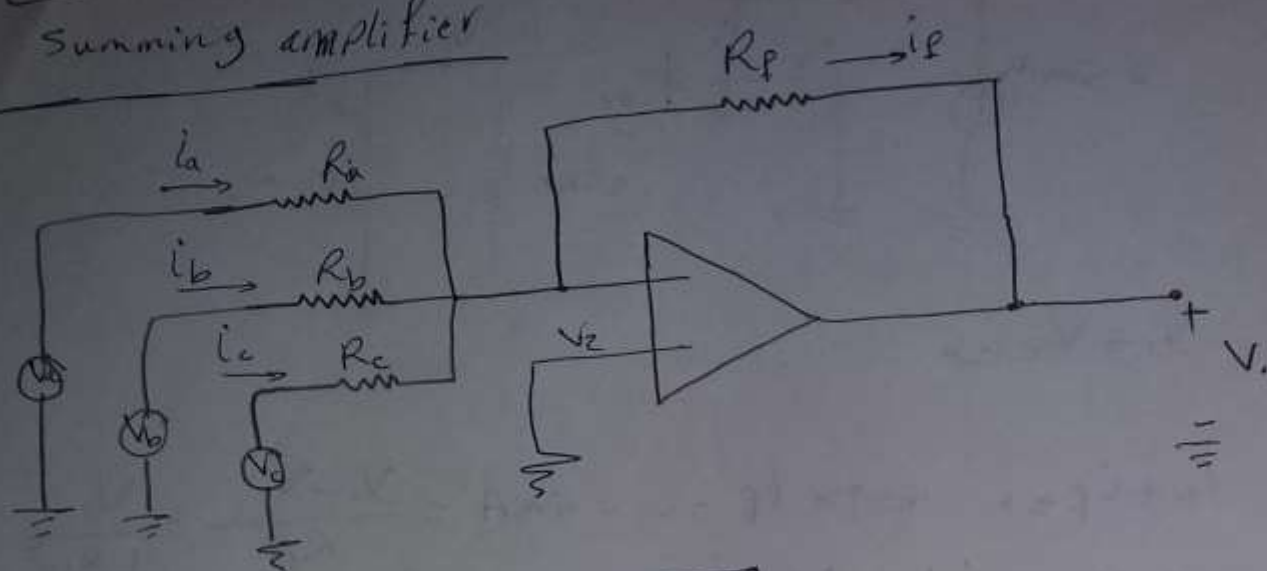
$$V_o = -\frac{R_f}{R_s} V_s$$

inverted



2

Summing amplifier



$$i_f + i_a + i_b + i_c = 0$$

$$V_1 = V_2 = 0$$

$$\frac{V_o}{R_f} + \frac{V_a}{R_a} + \frac{V_b}{R_b} + \frac{V_c}{R_c} = 0$$

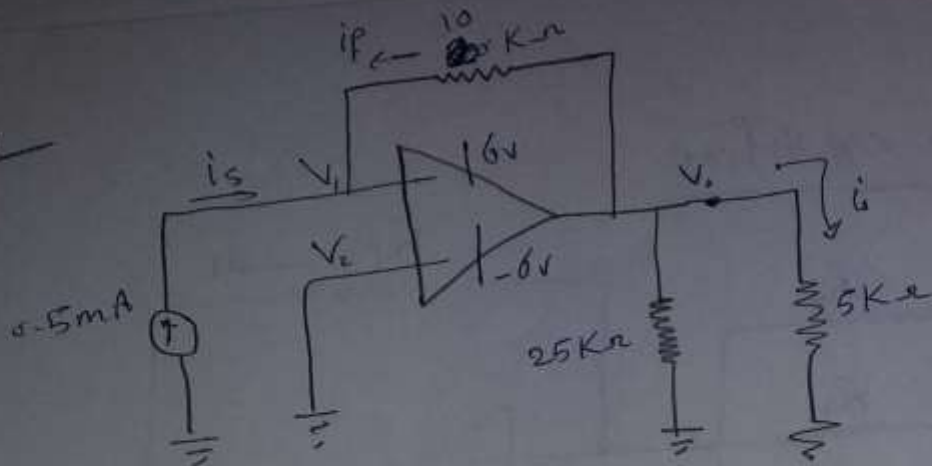
$$V_o = \left( -\frac{V_a}{R_a} - \frac{V_b}{R_b} - \frac{V_c}{R_c} \right) R_f$$

$$V_o = - \left( \frac{R_f}{R_a} V_a + \frac{R_f}{R_b} V_b + \frac{R_f}{R_c} V_c \right)$$

if  $R_a = R_b = R_c = R_f$

$$V_o = - (V_a + V_b + V_c)$$

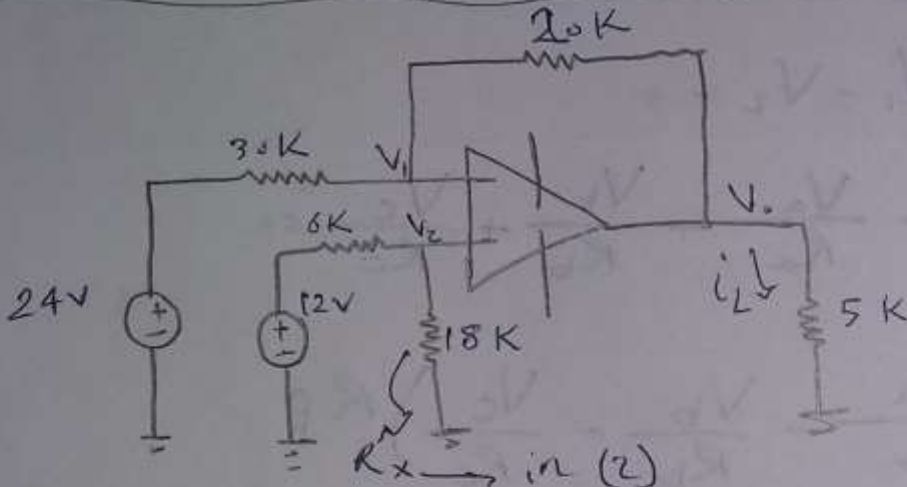
Find  $i_o$



$$V_1 = V_2 = 0$$

$$i_s + i_f = 0 \Rightarrow i_f = -0.5 \text{ mA} = \frac{V_o - V_1}{R_f} = \frac{V_o}{10 \times 10^3}$$

$$V_o = -5 \text{ V} \rightarrow i_o = \frac{V_o}{5} = -1 \text{ mA}$$



$$V_1 = V_2 = 12 \times \frac{18}{18 + 6} = 9 \text{ V}$$

$$i_s + i_f = 0$$

$$\frac{24 - 9}{30 \times 10^3} + \frac{V_o - 9}{20 \times 10^3} = 0$$

$$V_o = -1 \text{ V}$$

$$i_L = \frac{V_o}{5 \times 10^3} = -0.2 \text{ mA}$$

(c) Find value of  $R_x$  so that (op. amp) not saturated

$$\frac{24 - V_1}{30 \times 10^3} + \frac{V_o - V_1}{20 \times 10^3} = 0$$

$$\frac{24}{30} - \frac{V_1}{30} + \frac{V_o}{20} - \frac{V_1}{20} = 0$$

$$V_1 \left( \frac{1}{30} + \frac{1}{20} \right) = \frac{24}{30} + \frac{V_o}{20}$$

$$V_o = 5V \Rightarrow V_1 = \frac{\frac{24}{30} - \frac{1}{4}}{\frac{1}{30} + \frac{1}{20}} = 12 - \frac{R_x}{R_x + 5 \times 10^3}$$

$$V_o = 5V \Rightarrow V_1 = 0$$

$$\therefore 0 < R_x < \infty$$